## The Multivariate Gaussian Distribution

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A *d*-dimensional random vector  $X = (X_1, \ldots, X_d)$  has a *multivariate Gaussian distribution* or *normal* distribution on  $\mathcal{R}^d$  if there is a vector  $\xi \in \mathcal{R}^d$  and a  $d \times d$  matrix  $\Sigma$  such that

$$\lambda^{ op} X \sim \mathcal{N}(\lambda^{ op} \xi, \lambda^{ op} \Sigma \lambda) \quad \text{for all } \lambda \in R^d.$$
 (1)

We then write  $X \sim \mathcal{N}_d(\xi, \Sigma)$ .

Taking  $\lambda = e_i$  or  $\lambda = e_i + e_j$  where  $e_i$  is the unit vector with *i*-th coordinate 1 and the remaining equal to zero yields:

$$X_i \sim \mathcal{N}(\xi_i, \sigma_{ii}), \quad \text{Cov}(X_i, X_j) = \sigma_{ij}.$$

Hence  $\xi$  is the *mean vector* and  $\Sigma$  the *covariance matrix* of the distribution.

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The definition (1) makes sense if and only if  $\lambda^{\top} \Sigma \lambda \ge 0$ , i.e. if  $\Sigma$  is *positive semidefinite*. Note that we have allowed distributions with variance zero.

The multivariate moment generating function of X can be calculated using the relation (1) as

$$m_d(\lambda) = E\{e^{\lambda^{\top}X}\} = e^{\lambda^{\top}\xi + \lambda^{\top}\Sigma\lambda/2}$$

where we have used that the univariate moment generating function for  $\mathcal{N}(\mu,\sigma^2)$  is

$$m_1(t) = e^{t\mu + \sigma^2 t^2/2}$$

and let t = 1,  $\mu = \lambda^{\top} \xi$ , and  $\sigma^2 = \lambda^{\top} \Sigma \lambda$ .

In particular this means that a multivariate Gaussian distribution is determined by its mean vector and covariance matrix.

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Assume  $X^{\top} = (X_1, X_2, X_3)$  with  $X_i$  independent and  $X_i \sim \mathcal{N}(\xi_i, \sigma_i^2)$ . Then

$$\lambda^{\top} \mathbf{X} = \lambda_1 \mathbf{X}_1 + \lambda_2 \mathbf{X}_2 + \lambda_3 \mathbf{X}_3 \sim \mathcal{N}(\mu, \tau^2)$$

with

$$\mu = \lambda^{\top} \xi = \lambda_1 \xi_1 + \lambda_2 \xi_2 + \lambda_3 \xi_3, \quad \tau^2 = \lambda_1^2 \sigma_1^2 + \lambda_2^2 \sigma_2^2 + \lambda_3^2 \sigma_3^2.$$

Hence  $X \sim \mathcal{N}_3(\xi, \Sigma)$  with  $\xi^{ op} = (\xi_1, \xi_2, \xi_3)$  and

$$\Sigma = \left(egin{array}{ccc} \sigma_1^2 & 0 & 0 \ 0 & \sigma_2^2 & 0 \ 0 & 0 & \sigma_3^2 \end{array}
ight)$$

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If  $\Sigma$  is *positive definite*, i.e. if  $\lambda^{\top} \Sigma \lambda > 0$  for  $\lambda \neq 0$ , the distribution has density on  $\mathcal{R}^d$ 

$$f(x \mid \xi, \Sigma) = (2\pi)^{-d/2} (\det K)^{1/2} e^{-(x-\xi)^\top K (x-\xi)/2}, \qquad (2)$$

where  $K = \Sigma^{-1}$  is the *concentration matrix* of the distribution. Since a positive semidefinite matrix is positive definite if and only if it is invertible, we then also say that  $\Sigma$  is *regular*.

If  $X_1, \ldots, X_d$  are independent and  $X_i \sim \mathcal{N}(\xi_i, \sigma_i^2)$  their joint density has the form (2) with  $\Sigma = \text{diag}(\sigma_i^2)$  and  $\mathcal{K} = \Sigma^{-1} = \text{diag}(1/\sigma_i^2)$ .

Hence vectors of independent Gaussians are multivariate Gaussian.

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In the bivariate case it is traditional to write

$$\Sigma = \left( egin{array}{cc} \sigma_1^2 & \sigma_1\sigma_2
ho \ \sigma_1\sigma_2
ho & \sigma_2^2 \end{array} 
ight),$$

with  $\rho$  being the *correlation* between  $X_1$  and  $X_2$ . Then

$$\det(\Sigma) = \sigma_1^2 \sigma_2^2 (1 - \rho^2) = \det(K)^{-1}$$

and

$$\mathcal{K} = rac{1}{\sigma_1^2 \sigma_2^2 (1-
ho^2)} \left( egin{array}{cc} \sigma_2^2 & -\sigma_1 \sigma_2 
ho \ -\sigma_1 \sigma_2 
ho & \sigma_1^2 \end{array} 
ight).$$

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Thus the density becomes

$$f(x \mid \xi, \Sigma) = \frac{1}{2\pi\sigma_1\sigma_2\sqrt{(1-\rho^2)}} \\ \times e^{-\frac{1}{2(1-\rho^2)}\left\{\frac{(x_1-\xi_1)^2}{\sigma_1^2} - 2\rho\frac{(x_1-\xi_1)(x_2-\xi_2)}{\sigma_1\sigma_2} + \frac{(x_2-\xi_2)^2}{\sigma_2^2}\right\}}$$

The contours of this density are ellipses and the corresponding density is bell-shaped with maximum in  $(\xi_1, \xi_2)$ .

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The marginal distributions of a vector X can all be Gaussian without the joint being multivariate Gaussian:

For example, let  $X_1 \sim \mathcal{N}(0,1)$ , and define  $X_2$  as

$$X_2 = \left\{egin{array}{cc} X_1 & ext{if } |X_1| > c \ -X_1 & ext{otherwise.} \end{array}
ight.$$

Then, using the symmetry of the univariate Gausssian distribution,  $X_2$  is also distributed as  $\mathcal{N}(0, 1)$ .

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However, the joint distribution is not Gaussian unless c = 0 since, for example,  $Y = X_1 + X_2$  satisfies

$$P(Y = 0) = P(X_2 = -X_1) = P(|X_1| \le c) = \Phi(c) - \Phi(-c).$$

Note that for c = 0, the correlation  $\rho$  between  $X_1$  and  $X_2$  is 1 whereas for  $c = \infty$ ,  $\rho = -1$ .

It follows that there is a value of c so that  $X_1$  and  $X_2$  are uncorrelated, and still not jointly Gaussian.

Adding independent Gaussians Linear transformations Marginal distributions Conditional distributions Example

Adding two independent Gaussians yields a Gaussian: If  $X \sim \mathcal{N}_d(\xi_1, \Sigma_1)$  and  $X_2 \sim \mathcal{N}_d(\xi_2, \Sigma_2)$  and  $X_1 \perp \perp X_2$  $X_1 + X_2 \sim \mathcal{N}_d(\xi_1 + \xi_2, \Sigma_1 + \Sigma_2).$ 

To see this, just note that

$$\lambda^{\top}(X_1 + X_2) = \lambda^{\top}X_1 + \lambda^{\top}X_2$$

and use the univariate addition property.

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Linear transformations preserve multivariate normality: If A is an  $r \times d$  matrix,  $b \in \mathbb{R}^r$  and  $X \sim \mathcal{N}_d(\xi, \Sigma)$ , then

$$Y = AX + b \sim \mathcal{N}_r(A\xi + b, A\Sigma A^{\top}).$$

Again, just write

$$\gamma^{\top} Y = \gamma^{\top} (AX + b) = (A^{\top} \gamma)^{\top} X + \gamma^{\top} b$$

and use the corresponding univariate result.

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Partition X into into  $X_1$  and  $X_2$ , where  $X_1 \in \mathbb{R}^r$  and  $X_2 \in \mathbb{R}^s$  with r + s = d.

Partition mean vector, concentration and covariance matrix accordingly as

$$\xi = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix}, \quad \mathcal{K} = \begin{pmatrix} \mathcal{K}_{11} & \mathcal{K}_{12} \\ \mathcal{K}_{21} & \mathcal{K}_{22} \end{pmatrix}, \quad \Sigma = \begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix}$$

so that  $\Sigma_{11}$  is  $r \times r$  and so on. Then, if  $X \sim \mathcal{N}_d(\xi, \Sigma)$ 

$$X_2 \sim \mathcal{N}_s(\xi_2, \Sigma_{22}).$$

This follows simply from the previous fact using the matrix

$$A=\left(0_{sr}\ I_{s}\right).$$

where  $0_{sr}$  is an  $s \times r$  matrix of zeros and  $I_s$  is the  $s \times s$  identity matrix.

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## If $\Sigma_{22}$ is regular, it further holds that

$$X_1 | X_2 = x_2 \sim \mathcal{N}_r(\xi_{1|2}, \Sigma_{1|2}),$$

where

$$\xi_{1|2} = \xi_1 + \Sigma_{12} \Sigma_{22}^{-1} (x_2 - \xi_2)$$
 and  $\Sigma_{1|2} = \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}.$ 

In particular,  $\Sigma_{12} = 0$  if and only if  $X_1$  and  $X_2$  are independent.

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To see this, we simply calculate the conditional density.

$$\begin{split} f(x_1 \mid x_2) &\propto f_{\xi, \Sigma}(x_1, x_2) \\ &\propto \exp\left\{-(x_1 - \xi_1)^\top K_{11}(x_1 - \xi_1)/2 - (x_1 - \xi_1)^\top K_{12}(x_2 - \xi_2)\right\}. \end{split}$$

The linear term involving  $x_1$  has coefficient equal to

$$K_{11}\xi_1 - K_{12}(x_2 - \xi_2) = K_{11} \left\{ \xi_1 - K_{11}^{-1}K_{12}(x_2 - \xi_2) \right\}.$$

Using the matrix identities

$$K_{11}^{-1} = \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21} \tag{3}$$

and

$$K_{11}^{-1}K_{12} = -\Sigma_{12}\Sigma_{22}^{-1},\tag{4}$$

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we find

$$f(x_1 | x_2) \propto \exp\left\{-(x_1 - \xi_{1|2})^{\top} K_{11}(x_1 - \xi_{1|2})/2\right\}$$

and the result follows.

From the identities (3) and (4) it follows in particular that then the conditional expectation and concentrations also can be calculated as

$$\xi_{1|2} = \xi_1 - {K_{11}^{-1}} {K_{12}} (x_2 - \xi_2)$$
 and  ${K_{1|2}} = {K_{11}}$ 

Note that the marginal covariance is simply expressed in terms of  $\Sigma$  whereas the conditional concentration is simply expressed in terms of K. Further,  $X_1$  and  $X_2$  are independent if and only if  $K_{12} = 0$ , giving  $K_{12} = 0$  if and only if  $\Sigma_{12} = 0$ .

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Consider  $\mathcal{N}_3(0,\Sigma)$  with covariance matrix

$$\Sigma = \left( egin{array}{cccc} 1 & 1 & 1 \ 1 & 2 & 1 \ 1 & 1 & 2 \end{array} 
ight).$$

The concentration matrix is

$$\mathcal{K} = \Sigma^{-1} = \left( egin{array}{ccc} 3 & -1 & -1 \ -1 & 1 & 0 \ -1 & 0 & 1 \end{array} 
ight).$$

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The marginal distribution of  $(X_2, X_3)$  has covariance and concentration matrix

$$\Sigma_{23} = \left( egin{array}{cc} 2 & 1 \ 1 & 2 \end{array} 
ight), \quad (\Sigma_{23})^{-1} = rac{1}{3} \left( egin{array}{cc} 2 & -1 \ -1 & 2 \end{array} 
ight)$$

The conditional distribution of  $(X_1, X_2)$  given  $X_3$  has concentration and covariance matrix

$${\cal K}_{12}=\left( egin{array}{cc} 3 & -1 \ -1 & 1 \end{array} 
ight), \quad {\Sigma}_{12|3}=({\cal K}_{12})^{-1}=rac{1}{2}\left( egin{array}{cc} 1 & 1 \ 1 & 3 \end{array} 
ight).$$

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Similarly,  $V(X_1 | X_2, X_3) = 1/k_{11} = 1/3$ , etc.

Trace of matrix Sample with known mean Maximizing the likelihood

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A square matrix A has trace

$$\mathsf{tr}(A) = \sum_i a_{ii}.$$

The trace has a number of properties:

- 1.  $\operatorname{tr}(\gamma A + \mu B) = \gamma \operatorname{tr}(A) + \mu \operatorname{tr}(B)$  for  $\gamma, \mu$  being scalars; 2.  $\operatorname{tr}(A) = \operatorname{tr}(A^{\top})$ ; 3.  $\operatorname{tr}(AB) = \operatorname{tr}(BA)$
- 4.  $tr(A) = \sum_{i} \lambda_{i}$  where  $\lambda_{i}$  are the *eigenvalues* of A.

Trace of matrix Sample with known mean Maximizing the likelihood

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For symmetric matrices the last statement follows from taking an orthogonal matrix O so that  $OAO^{\top} = \text{diag}(\lambda_1, \dots, \lambda_d)$  and using

$$\operatorname{tr}(OAO^{\top}) = \operatorname{tr}(AO^{\top}O) = \operatorname{tr}(A).$$

The trace is thus *orthogonally invariant*, as is the determinant:

$$\det(OAO^{\top}) = \det(O) \det(A) \det(O^{\top}) = 1 \det(A)1 = \det(A).$$

There is an important trick that we shall use again and again: For  $\lambda \in \mathcal{R}^d$  $\lambda^\top A \lambda = tr(\lambda^\top A \lambda) = tr(A \lambda \lambda^\top)$ 

since  $\lambda^{\top} A \lambda$  is a scalar.

Trace of matrix Sample with known mean Maximizing the likelihood

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Consider the case where  $\xi = 0$  and a sample  $X^1 = x^1, \ldots, X^n = x^n$  from a multivariate Gaussian distribution  $\mathcal{N}_d(0, \Sigma)$  with  $\Sigma$  regular. Using (2), we get the likelihood function

$$L(K) = (2\pi)^{-nd/2} (\det K)^{n/2} e^{-\sum_{\nu=1}^{n} (x^{\nu})^{\top} K x^{\nu}/2}$$
  

$$\propto (\det K)^{n/2} e^{-\sum_{\nu=1}^{n} \operatorname{tr} \{K x^{\nu} (x^{\nu})^{\top}\}/2}$$
  

$$= (\det K)^{n/2} e^{-\operatorname{tr} \{K \sum_{\nu=1}^{n} x^{\nu} (x^{\nu})^{\top}\}/2}$$
  

$$= (\det K)^{n/2} e^{-\operatorname{tr} (Kw)/2}.$$
(5)

where

$$W = \sum_{\nu=1}^n X^\nu (X^\nu)^\top$$

is the matrix of *sums of squares and products*.

Trace of matrix Sample with known mean Maximizing the likelihood

Writing the trace out

$${
m tr}({
m {\it KW}}) = \sum_i \sum_j k_{ij} W_{ji}$$

emphasizes that it is linear in both K and W and we can recognize this as a linear and canonical exponential family with K as the canonical parameter and -W/2 as the canonical sufficient statistic. Thus, the likelihood equation becomes

$$\mathbf{E}(-W/2) = -n\Sigma/2 = -w/2$$

since  $\mathbf{E}(W) = n\Sigma$ . Solving, we get

$$\hat{K}^{-1} = \hat{\Sigma} = w/n$$

in analogy with the univariate case.

Trace of matrix Sample with known mean Maximizing the likelihood

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Rewriting the likelihood function as

$$\log L(K) = \frac{n}{2} \log(\det K) - \operatorname{tr}(Kw)/2$$

we can of course also differentiate to find the maximum, leading to

$$\frac{\partial}{\partial k_{ij}}\log(\det K)=w_{ij}/n,$$

which in combination with the previous result yields

$$rac{\partial}{\partial K}\log(\det K)=K^{-1}.$$

The latter can also be derived directly by writing out the determinant, and it holds for any non-singular square matrix, i.e. one which is not necessarily positive definite.