Markov properties for directed acyclic graphs

Aarhus University, Fall 2003, Lecture 2 and 3

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Directed acyclic graphs

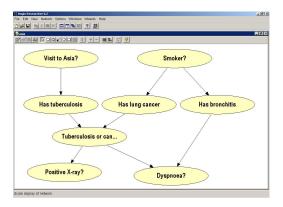
A directed acyclic graph \mathcal{D} over a finite set V is a graph with all edges being directed, no multiple edges, and no directed cycles.

Absence of directed cycles means that, following arrows in the graph, it is impossible to return to any point.

Graphical models based on DAGs have proved fundamental and useful in a wealth of interesting applications, including expert systems, genetics, complex biomedical statistics, causal analysis, and machine learning.

The remainder of this course will give a glimpse into these applications.

Example of a directed graphical model



Factorisation with respect to a DAG

A probability distribution P over $\mathcal{X} = \mathcal{X}_V$ factorizes over a DAG \mathcal{D} if it has density f w.r.t. a product measure $\mu = \bigotimes_{v \in V} \mu_v$, where f has the form

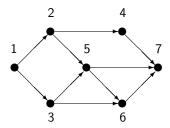
(DF):
$$f(x) = \prod_{v \in V} k_v(x_v | x_{pa(v)})$$

where $k_v \ge 0$ and $\int_{\mathcal{X}_v} k_v(x_v | x_{pa(v)}) d\mu_v(x_v) = 1$. (DF) is equivalent to (DF^{*}), where

$$(\mathsf{DF}^*): \quad f(x) = \prod_{v \in V} f(x_v \mid x_{\mathrm{pa}(v)}),$$

i.e. it follows from (DF) that k_v in fact are conditional densities. Proof by induction!

Example of DAG factorization



The above graph corresponds to the factorization

$$\begin{aligned} f(x) &= f(x_1)f(x_2 \mid x_1)f(x_3 \mid x_1)f(x_4 \mid x_2) \\ &\times f(x_5 \mid x_2, x_3)f(x_6 \mid x_3, x_5)f(x_7 \mid x_4, x_5, x_6). \end{aligned}$$

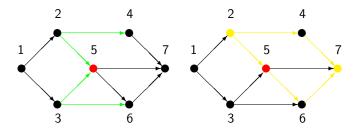
Separation in DAGs

A *trail* τ from node a to node b in a DAG D is *blocked* by S if it contains a node $n \in \tau$ such that

- either $n \in S$ and edges of τ do not meet head-to-head at n, or
- n and all its descendants are not in S, and edges of τ meet head-to-head at n.

A trail that is not blocked is *active*. Two subsets A and B of nodes are *d*-separated by S if all trails from A to B are blocked by S. We write $A \perp_{\mathcal{D}} B \mid S$.

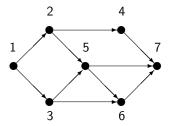
Separation by example



For $S = \{5\}$, the trail (4, 2, 5, 3, 6) is *active*, whereas the trails (4, 2, 5, 6) and (4, 7, 6) are *blocked*.

For $S = \{3, 5\}$, they are all blocked.

Returning to example



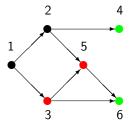
Hence $4 \perp_{\mathcal{D}} 6 \mid 3, 5$, but it is *not* true that $4 \perp_{\mathcal{D}} 6 \mid 5$ nor that $4 \perp_{\mathcal{D}} 6$.

Alternative equivalent separation

- 1. Reduce to subgraph induced by ancestral set of $A \cup B \cup S$
- 2. Add undirected edges between unmarried parents in this subgraph
- 3. Drop directions on all edges. Process 2 and 3 is known as *moralization* and result is *moral graph*.
- Say that S m-separates A from B and write A ⊥_m B | S if and only if S separates A from B in this undirected graph.

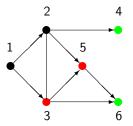
It then holds that $A \perp_m B \mid S$ if and only if $A \perp_D B \mid S$. Sometimes (but not always) easier to use.

Forming ancestral set



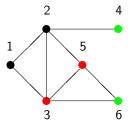
The subgraph induced by all ancestors of nodes involved in the query $4 \perp_m 6 \mid 3, 5$?

Adding links between unmarried parents



Adding an undirected edge between 2 and 3 with common child 5 in the subgraph induced by all ancestors of nodes involved in the query $4 \perp_m 6 \mid 3, 5$?

Dropping directions



Since $\{3,5\}$ separates 4 from 6 in this graph, we can conclude that $4 \perp_m 6 \mid 3, 5$

Properties of *d***-separation**

It holds for any DAG \mathcal{D} that $\perp_{\mathcal{D}}$ satisfies graphoid axioms.

Clearly, this is then also true for \perp_m .

To show this is true, it is sometimes easy to use \perp_m , sometimes $\perp_{\mathcal{D}}$.

For example, (S2) is trivial for $\perp_{\mathcal{D}}$, whereas (S5) is trivial for \perp_m .

So, equivalence of $\perp_{\mathcal{D}}$ and \perp_m is useful.

Local and global directed Markov properties

A semigraphoid relation \perp_{σ} satisfies

(DL) the local Markov property if
∀α ∈ V : α ⊥_σ (nd(α) \ pa(α)) | pa(α);
(DG) the global Markov property if

$$A \perp_{\mathcal{D}} B \mid S \implies A \perp_{\sigma} B \mid S.$$

For a DAG it holds that (DG) \iff (DL) also if f(x) = 0 is allowed.

There is also a pairwise property (DP). But it is less natural, it holds that (DL) \implies (DP), but not conversely unless f(x) > 0.

Markov properties and factorization

In contrast to the undirected case, it holds for all f that (DF) holds if and only if \bot satisfies (DG), so global Markov property and factorisation property is equivalent:

Thus, in the directed case

$$(\mathsf{DF})\iff (\mathsf{DG})\iff (\mathsf{DL})$$

and this is true whether f > 0 or not.

Further properties

If P factorizes over $\mathcal{D},$ it factorizes over the moralised graph \mathcal{D}^m

This is seen directly from the factorization:

$$f(x) = \prod_{v \in V} f(x_v \,|\, x_{pa(v)}) = \prod_{v \in V} \psi_{\{v\} \cup pa(v)}(x),$$

since $\{v\} \cup pa(v)$ are all complete in \mathcal{D}^m .

Hence if P satisfies any of the directed Markov properties w.r.t. \mathcal{D} , it satisfies all Markov properties for \mathcal{D}^m , so e.g. any Markov chain is also a Markov field.

Perfect DAGs

A DAG $\mathcal D$ is *perfect* if all parents are married. For a perfect DAG $\mathcal D$:

P satisfies (DG) w.r.t \mathcal{D} if and only if it satisfies (G) w.r.t. its skeleton $\sigma(\mathcal{D})$.

The *skeleton* is the undirected graph obtained from $\ensuremath{\mathcal{D}}$ by ignoring directions.

An undirected graph G can be oriented as a perfect DAG if and only if G is chordal, or triangulated, i.e. has rigid circuits,

An undirected graph is *chordal* if all cycles of length ≥ 4 have chords. Also known as *decomposable*.

Ancestral marginals

Consider a DAG \mathcal{D} and an *ancestral subset* $A \subseteq V$.

If P factorizes w.r.t. \mathcal{D} , it factorizes w.r.t. \mathcal{D}_A .

Proof by induction, using that if A is ancestral and $A \neq V$, there is a terminal vertex v_0 with $v_0 \notin A$.

It now follows, that if P factorizes w.r.t. \mathcal{D} :

$$A \perp_m B \mid S \implies A \perp\!\!\!\perp B \mid S.$$

The equivalence of (DF), (DG) and (DL) now follows easily.

Only difficult proof of results on overheads is the equivalence of $\perp_{\mathcal{D}}$ and \perp_m . Proof in Lauritzen (1996) needs to allow self-intersecting paths to be correct.