- 1. Linear logistic regression
 - (a) The joint density is

$$f(x;\alpha,\beta) = \prod_{i} \frac{e^{(\alpha+\beta d_{i})x_{i}}}{1+e^{\alpha+\beta d_{i}}} = \frac{e^{\alpha \sum_{i} x_{i}+\beta \sum_{i} d_{i}x_{i}}}{\prod_{i}(1+e^{\alpha+\beta d_{i}})}$$
$$= e^{\alpha \sum_{i} x_{i}+\beta \sum_{i} d_{i}x_{i}-\sum_{i} \log(1+e^{\alpha+\beta d_{i}})}.$$

This has the form of a canonical exponential family with canonical sufficient statistic $t(X) = (\sum_i X_i, \sum_i X_i d_i)$ and log-normalizing constant

$$c(\alpha,\beta) = \sum_{i} \log(1 + e^{\alpha + \beta d_i})$$

(b) The likelihood equation for the parameters α and β is determined by equating the canonical statistics to their expectations. We have

$$\mathbf{E}(X_i) = p_i = \frac{e^{\alpha + \beta d_i}}{1 + e^{\alpha + \beta d_i}}$$

so the likelihood equations are

$$\sum_{i} x_i = \mathbf{E}(\sum_{i} X_i) = \sum_{i} \frac{e^{\alpha + \beta d_i}}{1 + e^{\alpha + \beta d_i}}, \quad \sum_{i} x_i d_i = \mathbf{E}(\sum_{i} X_i d_i) = \sum_{i} \frac{d_i e^{\alpha + \beta d_i}}{1 + e^{\alpha + \beta d_i}}$$

Expressing this in terms of $p_i = \mathbf{E}(X_i)$ yields the alternative expressions

$$\sum_{i} x_i = \sum_{i} p_i, \quad \sum_{i} x_i d_i = \sum_{i} p_i d_i.$$

(c) In the case where it is known that $\alpha = 0$ we also have a canonical exponential family with $t_2(X) = \sum_i X_i d_i$ as canonical statistic. The Fisher information for β is found by differentiating the log-normalizing constant $c(0, \beta)$ twice to yield

$$i(\beta) = \sum_{i} \frac{d_i^2 e^{\beta d_i} - (d_i e^{\beta d_i})^2}{(1 + e^{\beta d_i})^2} = \sum_{i} d_i^2 p_i (1 - p_i) = \mathbf{V}(\sum_{i} X_i d_i)$$

and the asymptotic variance of $\hat{\beta}$ is $1/i(\beta)$.

(d) The iterative step for Fisher's scoring method in the case where $\alpha = 0$ is known is

$$\beta \leftarrow \beta + \frac{\sum_i (x_i - p_i) d_i}{\sum_i d_i^2 p_i (1 - p_i)}$$

- (e) The iterative step for the Newton-Raphson method, when $\alpha = 0$ is known is identical to that in the method of scoring since this is a canonical exponential family.
- (f) To write the iterative step for Fisher's method of scoring in the case where both α and β are unknown we need the full information matrix, obtained by differentiation of the log-normalizing constant $c(\alpha, \beta)$ or—whichever is easier— by calculating the covariance matrix of the canonical statistic. With the short notation introduced earlier, this gives

$$i(\alpha,\beta) = \begin{pmatrix} \mathbf{V}(\sum_{i} X_{i}) & \operatorname{Cov}(\sum_{i} X_{i}, \sum_{i} d_{i} X_{i}) \\ \operatorname{Cov}(\sum_{i} X_{i}, \sum_{i} d_{i} X_{i}) & \mathbf{V}(\sum_{i} d_{i} X_{i}) \end{pmatrix}$$
$$= \begin{pmatrix} \sum_{i} \mathbf{V}(X_{i}) & \sum_{i} \operatorname{Cov}(X_{i}, d_{i} X_{i}) \\ \sum_{i} \operatorname{Cov}(X_{i}, d_{i} X_{i}) & \sum_{i} \mathbf{V}(d_{i} X_{i}) \end{pmatrix}$$
$$= \begin{pmatrix} \sum_{i} p_{i}(1-p_{i}) & \sum_{i} d_{i} p_{i}(1-p_{i}) \\ \sum_{i} d_{i} p_{i}(1-p_{i}) & \sum_{i} d_{i}^{2} p_{i}(1-p_{i}) \end{pmatrix}.$$

- (g) The asymptotic covariance matrix of $(\hat{\alpha}, \hat{\beta})$ is given by the inverse of the information matrix calculated above. No specific simplication is obtained.
- 2. Deconvolution of Poisson signals.
 - (a) The joint density is

$$f(y;\alpha,\beta) = \prod_{i} \frac{(\beta + \alpha d_{i})^{y_{i}}}{y_{i}!} e^{-\beta - \alpha d_{i}}.$$

For $\beta = 1$ we get

$$f(y;\alpha) = \prod_{i} \frac{(1+\alpha d_i)^{y_i}}{y_i!} e^{-1-\alpha d_i}$$

This is not a canonical exponential family. If we try to give it exponential form we could write

$$f(y;\alpha) = \left(\prod_{i} \frac{1}{y_i!}\right) e^{\sum_{i} y_i \log(1+\alpha d_i) - n - \alpha \sum_{i} d_i},$$

but $\log(1 + \alpha d_i)$ is not a linear function of any transformation of α .

(b) The score statistic for α is

$$S(\alpha) = \sum_{i} \frac{Y_i d_i}{1 + \alpha d_i} - \sum_{i} d_i = \sum_{i} \frac{d_i (Y_i - 1 - \alpha d_i)}{1 + \alpha d_i}.$$

(c) The Fisher information for α is found by differentiating yet another time and taking expectations

$$j(\alpha) = -S'(\alpha) = \sum_{i} \frac{Y_i d_i^2}{(1 + \alpha d_i)^2}.$$

Taking expectations yields

$$i(\alpha) = \sum_{i} \frac{d_i^2}{1 + \alpha d_i}.$$

(d) The iterative step for solving the likelihood equation by the Newton– Raphson method is

$$\alpha \leftarrow \alpha + \frac{S(\alpha)}{j(\alpha)} = \alpha + \frac{\sum_i \frac{d_i(Y_i - 1 - \alpha d_i)}{1 + \alpha d_i}}{\sum_i \frac{Y_i d_i^2}{(1 + \alpha d_i)^2}}.$$

(e) The iterative step for solving the likelihood equation by Fisher's scoring method replaces the observed information with the expected

$$\alpha \leftarrow \alpha + \frac{S(\alpha)}{i(\alpha)} = \alpha + \frac{\sum_{i} \frac{d_i(Y_i - 1 - \alpha d_i)}{1 + \alpha d_i}}{\sum_{i} \frac{d_i^2}{(1 + \alpha d_i)}}.$$

(f) For complete data the likelihood function becomes

$$f(b,x;\alpha) = \prod_{i} \frac{1}{b_i!} e^{-n} \prod_{i} \frac{(\alpha d_i)^{x_i}}{x_i!} e^{-\alpha d_i} = h(b,x,d) e^{\log \alpha \sum_{i} X_i - \alpha \sum_{i} d_i}.$$

This is a linear exponential family with canonical parameter $\theta = \log \alpha$ and the MLE of α is thus found by equating the canonical statistic to its expectation, i.e.

$$\sum_{i} x_{i} = \sum_{i} \alpha d_{i}; \quad \hat{\alpha} = \frac{\sum_{i} x_{i}}{\sum_{i} d_{i}}.$$
(1)

(g) The complete data log-likelihood is (ignoring an additive constant)

$$\log L(\alpha; X, B) = \log \alpha \sum_{i} X_{i} - \alpha \sum_{i} d_{i}.$$

The E-step of the EM algorithm finds the conditional expectation of this given the observed data, i.e.

$$\mathbf{E}\{\log L(\alpha; X, B) \mid Y\} = \log \alpha \sum_{i} \mathbf{E}\{X_i \mid Y\} - \alpha \sum_{i} d_i = \log \alpha \sum_{i} x_i^* - \alpha \sum d_i$$

where $x_i^* = \mathbf{E}(X_i | Y_i)$. Conditionally on Y_i , X_i follows a binomial distribution with parameters (Y_i, p_i) where

$$p_i = \frac{\mathbf{E}(X_i)}{\mathbf{E}(Y_i)} = \frac{\alpha d_i}{1 + \alpha d_i}$$

hence

$$x_i^* = \frac{\alpha Y_i d_i}{1 + \alpha d_i}$$

(h) The E-step calculates x_i^* as above, thus imputing the unobserved values of the radioactive emissions from the source.

The M-step calculates the MLE by replacing x_i by x_i^* in (1), i.e. updates α as

$$\alpha \leftarrow \frac{\sum_i x_i^*}{\sum_i d_i}.$$

(i) If the background intensity β is unknown as well, the complete data log-likelihood becomes

$$\log L(\alpha, \beta; X, B) = \log \beta \sum_{i} B_{i} - n\beta + \log \alpha \sum_{i} X_{i} - \alpha \sum_{i} d_{i}.$$

Thus for the E-step we should calculate

$$x_i^* = \frac{\alpha Y_i d_i}{\beta + \alpha d_i}, \quad b_i^* = Y_i - x_i^*$$

and then update (α, β) as

$$\alpha \leftarrow \frac{\sum_i x_i^*}{\sum_i d_i}, \quad \beta \leftarrow \frac{\sum_i b_i^*}{n}.$$