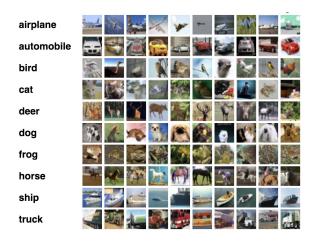
Algorithmic Foundations of Learning

Lecture 2 Maximal Inequalities and Rademacher complexity

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Offline statistical learning: prediction



Offline learning: prediction

Given a batch of observations (images & labels) interested in predicting the label of a new image

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Offline statistical learning: prediction

- 1. Observe training data Z_1, \ldots, Z_n i.i.d. from <u>unknown</u> distribution
- 2. Choose action $A \in \mathcal{A} \subseteq \mathcal{B}$
- 3. Suffer an expected/population loss/risk r(A), where

$$a \in \mathcal{B} \longrightarrow r(a) := \mathbf{E}\,\ell(a,Z)$$

with ℓ is an prediction loss function and Z is a new test data point

Goal: Minimize the estimation error defined by the following decomposition

$$\underbrace{r(A) - \inf_{a \in \mathcal{B}} r(a)}_{\text{excess risk}} = \underbrace{r(A) - \inf_{a \in \mathcal{A}} r(a) + \inf_{a \in \mathcal{A}} r(a) - \inf_{a \in \mathcal{B}} r(a)}_{\text{approximation error}}$$

as a function of n and notions of "complexity" of the set ${\mathcal A}$ of the function ℓ

Note: Estimation/Approximation trade-off, a.k.a. complexity/bias

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ERM and Uniform Learning

▶ A natural framework is given by the empirical risk minimization (ERM)

$$a \in \mathcal{B} \longrightarrow R(a) := \frac{1}{n} \sum_{i=1}^{n} \ell(a, Z_i)$$

▶ A natural algorithm is given by the minimizer of the ERM

$$A^* \in \operatorname*{argmin}_{a \in A} R(a)$$

▶ Uniform Learning: The estimation error is bounded by

$$\underbrace{r(A^\star) - r(a^\star)}_{\text{estimation error for ERM}} \leq \underbrace{\sup_{a \in \mathcal{A}} \{r(a) - R(a)\} + \sup_{a \in \mathcal{A}} \{R(a) - r(a)\}}_{\text{Statistics}}$$

- ► Statistical Learning deals with bounding the Statistics term (Vapnik 1995)
- ▶ Generalization Error: $r(a) R(a) \approx \frac{1}{n^{(\text{test})}} \sum_{i=1}^{n^{(\text{test})}} \ell(a, Z_i^{(\text{test})}) \frac{1}{n} \sum_{i=1}^n \ell(a, Z_i)$

Goal: derive bounds in expectation

► Goal:

$$\boxed{ \mathbf{E} \underbrace{r(A^\star) - r(a^\star)}_{\text{estimation error for ERM}} \lesssim \frac{f(\text{dimension})}{n^\alpha} }$$

▶ By uniform learning, it suffices to bound the suprema of random processes:

$$\mathbf{E} g(Z_1,\ldots,Z_n) \leq rac{f(\mathsf{dimension}, rac{\mathsf{complexity} \ \mathsf{of} \ \mathcal{A})}{n^lpha}$$

with
$$g(Z_1, ..., Z_n) = \sup_{a \in \mathcal{A}} \{ r(a) - R(a) \} = \sup_{a \in \mathcal{A}} \left\{ \mathbf{E}\ell(a, Z) - \frac{1}{n} \sum_{i=1}^n \ell(a, Z_i) \right\}$$

- ▶ We aim to derive a <u>uniform</u>, non-asymptotic Law of Large Numbers
- ▶ In machine learning, dimension can be $\gg 10^6$, e.g., number of pixels
- ▶ Ideally, $f(\text{dimension}) \ll \text{dimension}$, e.g., $f(\text{dimension}) \sim \log(\text{dimension})$
- ▶ Ideally, $\alpha = 1$ (fast rate)

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Hoeffding's Lemma (Lemma 2.1)

Let X be a bounded random variable $a \leq X - \mathbf{E}X \leq b$. Then, for any $\lambda \in \mathbb{R}$,

$$\mathbf{E}\,e^{\lambda(X-\mathbf{E}X)} \le e^{\lambda^2(b-a)^2/8}$$

Proof

• W.I.o.g., take $\mathbf{E}X = 0$. Let $\psi(\lambda) = \log \mathbf{E} e^{\lambda X}$

$$\psi'(\lambda) = \frac{\mathbf{E}[Xe^{\lambda X}]}{\mathbf{E}e^{\lambda X}} \qquad \psi''(\lambda) = \frac{\mathbf{E}[X^2e^{\lambda X}]}{\mathbf{E}e^{\lambda X}} - \left(\frac{\mathbf{E}[Xe^{\lambda X}]}{\mathbf{E}e^{\lambda X}}\right)^2$$

- $\psi''(\lambda)$ is the variance of X under the distribution $\mathbf{Q}(\mathrm{d}x) = \frac{e^{\lambda x}}{\mathbf{E} e^{\lambda X}} \mathbf{P}(\mathrm{d}x)$
- Fundamental Thm of Calculus: $\psi(\lambda) = \int_0^\lambda \int_0^\mu \psi''(\rho) d\rho d\mu \le \frac{\lambda^2 (b-a)^2}{8}$



Maximum of finitely many bounded random variables (Proposition 2.2)

Let X_1, \ldots, X_n be n <u>centered</u> random variables bounded in the interval [a, b].

$$\mathbf{E} \max_{i \in [n]} X_i \le \frac{b - a}{\sqrt{2}} \sqrt{\log n}$$

Proof

▶ $X = \max_{i \in [n]} X_i$. Exponentiate. Jensen's ineq. as $x \to e^{\lambda x}$ ($\lambda > 0$) is convex:

$$\mathbf{E}X = \frac{1}{\lambda} \log e^{\lambda \mathbf{E}X} \le \frac{1}{\lambda} \log \mathbf{E} e^{\lambda X}$$

▶ Bound maximum of non-negative numbers by the sum:

$$\mathbf{E} \, e^{\lambda X} = \mathbf{E} \, e^{\lambda \max_{i \in [n]} X_i} = \mathbf{E} \max_{i \in [n]} e^{\lambda X_i} \le \mathbf{E} \sum_{i=1}^n e^{\lambda X_i} = \sum_{i=1}^n \mathbf{E} \, e^{\lambda X_i}$$

Put everything together and use Hoeffding's lemma ($\mathbf{E} e^{\lambda X_i} \leq e^{\lambda^2 (b-a)^2/8}$):

$$\mathbf{E} \max_{i \in [n]} X_i \le \frac{1}{\lambda} \log \sum_{i=1}^n e^{\lambda^2 (b-a)^2/8} = \frac{1}{\lambda} \log n + \frac{\lambda (b-a)^2}{8}$$

▶ Optimizing the bound $\alpha/\lambda + \lambda\beta$ over $\lambda > 0$ yields the minimum is at $\lambda = \sqrt{\alpha/\beta}$ and the optimal value $2\sqrt{\alpha\beta} = (b-a)\sqrt{\log n/2}$

Bound in expectation for finitely-many actions

Bound in expectation (Proposition 2.3)

If the loss function ℓ is bounded by c, we have

$$\mathbf{E} \max_{a \in \mathcal{A}} \{ r(a) - R(a) \} \le c \frac{\sqrt{2 \log |\mathcal{A}|}}{\sqrt{n}}$$

Proof: Same as above, using the independence of the data Z_1, \ldots, Z_n (note that for each $a \in \mathcal{A}$, r(a) - R(a) is a centered random variable as $\mathbf{E}R(a) = r(a)$)

- $\qquad \qquad \mathbf{F} \text{ Recall wish: } \boxed{ \mathbf{E} \sup_{a \in \mathcal{A}} \{ r(a) R(a) \} \leq \frac{f(\mathsf{dimension}, \mathsf{complexity} \text{ of } \mathcal{A})}{n^{\alpha}} }$
- ▶ The dimension of the data is superseded by the boundedness assumption
- $ightharpoonup \alpha = 1/2$, slow rate
- ▶ When $|A| < \infty$, $\log |A|$ is a valid notion of complexity of the problem
- ▶ When $|A| = \infty$, upper bound is trivial and we need another notion of complexity

Rademacher complexity

Rademacher complexity (Definition 2.5)

The Rademacher complexity of a set $\mathcal{T} \subseteq \mathbb{R}^n$ is defined as

$$\boxed{\mathtt{Rad}(\mathcal{T}) := \mathbf{E} \sup_{t \in \mathcal{T}} \frac{1}{n} \sum_{i=1}^{n} \Omega_{i} t_{i}}$$

where $\Omega_1,\ldots,\Omega_n\in\{-1,1\}$ are i.i.d. uniform random variables (Rademacher)

- Measures of complexity: describes how well elements in \mathcal{T} can replicate the sign pattern of a uniform random signal in \mathbb{R}^n (see **Problem 1.5**)
- Useful properties:
 - $|\operatorname{Rad}(c\mathcal{T}+v)| = |c|\operatorname{Rad}(\mathcal{T})$ (Proposition 2.6)
 - $\bullet \ \ \, \boxed{\mathtt{Rad}(\mathcal{T}+\mathcal{T}')=\mathtt{Rad}(\mathcal{T})+\mathtt{Rad}(\mathcal{T}')} \ \ \, \text{(Proposition 2.7)}$

Rademacher complexity

Massart's Lemma (Lemma 2.9)

Let $\mathcal{T} \subseteq \mathbb{R}^n$ and let $v \in \mathbb{R}^n$ be any vector. We have

$$\mathrm{Rad}(\mathcal{T}) \leq \max_{t \in \mathcal{T}} \|t - v\|_2 \frac{\sqrt{2\log |\mathcal{T}|}}{n}$$

Proof: Similar to ones given above. **Problem 1.6**

Contraction property - Talagrand's Lemma (Lemma 2.10)

Let $\mathcal{T} \subseteq \mathbb{R}^n$. For each $i \in \{1, \dots, n\}$, let $f_i : \mathbb{R} \to \mathbb{R}$ be a γ -Lipschitz function. Then,

$$\mathtt{Rad}((f_1,\ldots,f_n)\circ\mathcal{T})\leq \gamma\,\mathtt{Rad}(\mathcal{T})$$

with $(f_1,\ldots,f_n)\circ\mathcal{T}:=\{(f_1(t_1),\ldots,f_n(t_n))\in\mathbb{R}^n:t\in\mathcal{T}\}$

Proof: Problem 1.7