# Statistical Machine Learning Hilary Term 2018

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Slide credits and other course material can be found at:

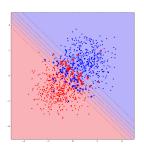
http://www.stats.ox.ac.uk/~palamara/SML18.html

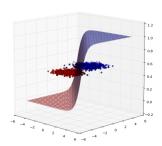
February 16, 2018

## Logistic regression

#### Review

- In LDA and QDA, we estimate p(x|y), but for classification we are mainly interested in p(y|x)
- Why not estimate that directly? Logistic regression<sup>1</sup> is a popular way of doing this.





<sup>&</sup>lt;sup>1</sup>Despite the name "regression", we are using it for classification!

## Linearity of log-odds and logistic function

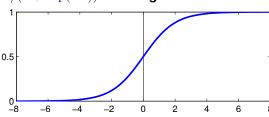
•  $a + b^{T}x$  models the **log-odds ratio**:

$$\log \frac{p(Y = +1|X = x; a, b)}{p(Y = -1|X = x; a, b)} = a + b^{\top} x.$$

• Solve explicitly for conditional class probabilities (using p(Y = +1|X = x; a, b) + p(Y = -1|X = x; a, b) = 1):

$$p(Y = +1|X = x; a, b) = \frac{1}{1 + \exp(-(a + b^{\top}x))} =: s(a + b^{\top}x)$$
$$p(Y = -1|X = x; a, b) = \frac{1}{1 + \exp(+(a + b^{\top}x))} = s(-a - b^{\top}x)$$

where  $s(z) = 1/(1 + \exp(-z))$  is the **logistic function**.



## Fitting the parameters of the hyperplane

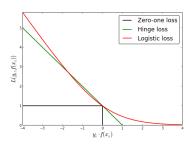
How to learn a and b given a training data set  $(x_i, y_i)_{i=1}^n$ ?

Consider maximizing the conditional log likelihood:

$$\ell(a,b) = \sum_{i=1}^{n} \log p(y_i|x_i) = \sum_{i=1}^{n} \log s(y_i(a+b^{\top}x_i)).$$

Equivalent to minimizing the empirical risk associated with the log loss:

$$\widehat{R}_{\log}(f_{a,b}) = \frac{1}{n} \sum_{i=1}^{n} -\log s(y_i(a + b^{\top}x_i)) = \frac{1}{n} \sum_{i=1}^{n} \log(1 + \exp(-y_i(a + b^{\top}x_i)))$$



## Logistic Regression

- Log-loss is differentiable, but it is not possible to find optimal a, b analytically.
- For simplicity, absorb a as an entry in b by appending '1' into x vector, as we did before.
- Objective function:

$$\widehat{R}_{\log} = \frac{1}{n} \sum_{i=1}^{n} -\log s(y_i x_i^{\top} b)$$

#### Logistic Function

$$s(-z) = 1 - s(z)$$

$$\nabla_z s(z) = s(z)s(-z)$$

$$\nabla_z \log s(z) = s(-z)$$

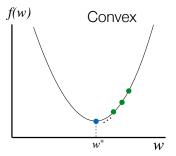
$$\nabla_z^2 \log s(z) = -s(z)s(-z)$$

Differentiate wrt b:

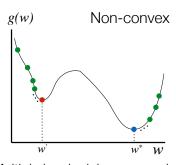
$$\begin{split} \nabla_b \widehat{R}_{\log} &= \frac{1}{n} \sum_{i=1}^n -s(-y_i x_i^\top b) y_i x_i \\ \nabla_b^2 \widehat{R}_{\log} &= \frac{1}{n} \sum_{i=1}^n s(y_i x_i^\top b) s(-y_i x_i^\top b) x_i x_i^\top \succeq 0. \end{split}$$

• We cannot set  $\nabla_b \hat{R}_{\log} = 0$  and solve: no closed form solution. We'll use numerical methods.

## Where Will We Converge?



Any local minimum is a global minimum



Multiple local minima may exist

Least Squares, Ridge Regression and Logistic Regression are all convex!

## Logistic Regression

- Hessian is positive-definite: objective function is convex and there is a single unique global minimum.
- Many different algorithms can find optimal b, e.g.:
  - Gradient descent:

$$b^{\text{new}} = b + \epsilon \frac{1}{n} \sum_{i=1}^{n} s(-y_i x_i^{\top} b) y_i x_i$$

Stochastic gradient descent:

$$b^{\mathsf{new}} = b + \epsilon_t \frac{1}{|I(t)|} \sum_{i \in I(t)} s(-y_i x_i^\top b) y_i x_i$$

where I(t) is a subset of the data at iteration t, and  $\epsilon_t \to 0$  slowly  $(\sum_t \epsilon_t = \infty, \sum_t \epsilon_t^2 < \infty)$ .

- Conjugate gradient, LBFGS and other methods from numerical analysis.
- Newton-Raphson:

$$b^{\mathsf{new}} = b - (\nabla_b^2 \widehat{R}_{\mathsf{log}})^{-1} \nabla_b \widehat{R}_{\mathsf{log}}$$

This is also called iterative reweighted least squares.

## Iterative reweighted least squares (IRLS)

• We can write gradient and Hessian in a more compact form. Define  $\mu_i = s(x_i^{\top}b)$ , and the diagonal matrix **S** with  $\mu_i(1-\mu_i)$  on its diagonal. Also define the vector **c** where  $c_i = \mathbb{1}(y_i = +1)$ . Then

$$\begin{split} \nabla_b \widehat{R}_{\log} = & \frac{1}{n} \sum_{i=1}^n -s(-y_i x_i^\top b) y_i x_i \\ = & \frac{1}{n} \sum_{i=1}^n x_i (\mu_i - c_i) \\ = & \mathbf{X}^\top (\mu - \mathbf{c}) \\ \nabla_b^2 \widehat{R}_{\log} = & \frac{1}{n} \sum_{i=1}^n s(y_i x_i^\top b) s(-y_i x_i^\top b) x_i x_i^\top \\ = & \mathbf{X}^\top \mathbf{S} \mathbf{X} \end{split}$$

## Iterative reweighted least squares (IRLS)

Let  $\mathbf{b}_t$  be the parameters after t "Newton steps".

The gradient and Hessian at step t are given by:

$$\mathbf{g}_t = \mathbf{X}^\mathsf{T}(\boldsymbol{\mu}_t - \mathbf{c}) = -\mathbf{X}^\mathsf{T}(\mathbf{c} - \boldsymbol{\mu}_t)$$
  
 $\mathbf{H}_t = \mathbf{X}^\mathsf{T}\mathbf{S}_t\mathbf{X}$ 

The Newton Update Rule is:

$$\begin{aligned} \mathbf{b}_{t+1} &= \mathbf{b}_t - \mathbf{H}_t^{-1} \mathbf{g}_t \\ &= \mathbf{b}_t + (\mathbf{X}^\mathsf{T} \mathbf{S}_t \mathbf{X})^{-1} \mathbf{X}^\mathsf{T} (\mathbf{c} - \boldsymbol{\mu}_t) \\ &= (\mathbf{X}^\mathsf{T} \mathbf{S}_t \mathbf{X})^{-1} \mathbf{X}^\mathsf{T} \mathbf{S}_t (\mathbf{X} \mathbf{b}_t + \mathbf{S}_t^{-1} (\mathbf{c} - \boldsymbol{\mu}_t)) \\ &= (\mathbf{X}^\mathsf{T} \mathbf{S}_t \mathbf{X})^{-1} \mathbf{X}^\mathsf{T} \mathbf{S}_t \mathbf{z}_t \end{aligned}$$

Where  $\mathbf{z}_t = \mathbf{X}\mathbf{b}_t + \mathbf{S}_t^{-1}(\mathbf{c} - \boldsymbol{\mu}_t)$ . Then  $\mathbf{b}_{t+1}$  is a solution of the "weighted least squares" problem:

minimise 
$$\sum_{i=1}^{N} S_{t,ii} (z_{t,i} - \mathbf{b}^{\mathsf{T}} \mathbf{x}_i)^2$$

## Linearly separable data

Assume that the data is linearly separable, i.e. there is a scalar  $\alpha$  and a vector  $\beta$  such that  $y_i(\alpha + \beta^\top x_i) > 0$ ,  $i = 1, \ldots, n$ . Let c > 0. The empirical risk for  $a = c\alpha$ ,  $b = c\beta$  is

$$\widehat{R}_{\log}(f_{a,b}) = \frac{1}{n} \sum_{i=1}^{n} \log(1 + \exp(-cy_i(\alpha + \beta^{\top} x_i)))$$

which can be made arbitrarily close to zero as  $c \to \infty$ , i.e. soft classification rule becomes  $\pm \infty$  (overconfidence)  $\to$  overfitting.

**Regularization** provides a solution to this problem.

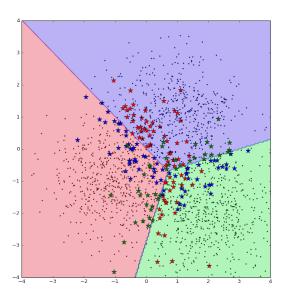
## Multi-class logistic regression

The **multi-class/multinomial** logistic regression uses the **softmax** function to model the conditional class probabilities  $p(Y = k | X = x; \theta)$ , for K classes  $k = 1, \ldots, K$ , i.e.,

$$p(Y = k|X = x; \theta) = \frac{\exp\left(w_k^\top x + b_k\right)}{\sum_{\ell=1}^K \exp\left(w_\ell^\top x + b_\ell\right)}.$$

Parameters are  $\theta=(b,W)$  where  $W=(w_{kj})$  is a  $K\times p$  matrix of weights and  $b\in\mathbb{R}^K$  is a vector of bias terms.

## Multi-class logistic regression

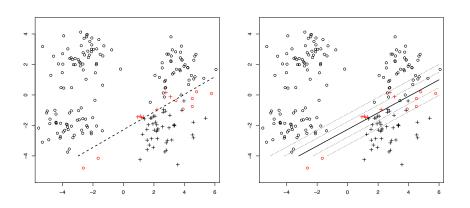


```
library(MASS)
## load crabs data
data(crabs)
ct <- as.numeric(crabs[,1])-1+2*(as.numeric(crabs[,2])-1)
## project into first two LD
cb.lda <- lda(log(crabs[,4:8]),ct)
cb.ldp <- predict(cb.lda)
x <- cb.ldp$x[,1:2]
y <- as.numeric(ct==0)
eqscplot(x,pch=2*y+1,col=y+1)</pre>
```

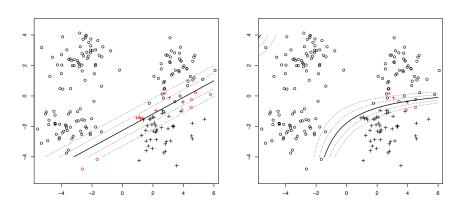
## visualize decision boundary

```
## logistic regression
xdf <- data.frame(x)
logreg <- glm(y ~ LD1 + LD2, data=xdf, family=binomial)
y.lr <- predict(logreg, type="response")</pre>
egscplot (x, pch=2*y+1, col=2-as.numeric(y==(v.lr>.5)))
y.lr.grid <- predict(logreg, newdata=gdf, type="response")</pre>
contour (qx1, qx2, matrix (y.lr.qrid, qm, qn),
   levels=c(.1,.25,.75,.9), add=TRUE,d=FALSE,ltv=3,lwd=1)
contour(gx1,gx2,matrix(v.lr.grid,gm,gn),
   levels=c(.5), add=TRUE,d=FALSE,ltv=1,lwd=2)
## logistic regression with quadratic interactions
logreg <- glm(y ~ (LD1 + LD2)^2, data=xdf, family=binomial)
y.lr <- predict(logreg, type="response")</pre>
egscplot(x,pch=2*v+1,col=2-as.numeric(v==(v.lr>.5)))
v.lr.grid <- predict(logreg,newdata=gdf,type="response")</pre>
contour (qx1, qx2, matrix (y.lr.qrid, qm, qn),
   levels=c(.1,.25,.75,.9), add=TRUE,d=FALSE,ltv=3,lwd=1)
contour(gx1,gx2,matrix(y.lr.grid,gm,gn),
   levels=c(.5), add=TRUE,d=FALSE,ltv=1,lwd=2)
```

#### Crab Dataset: Blue Female vs. rest



Comparing LDA and logistic regression.



Comparing logistic regression with and without quadratic interactions.

## Logistic regression Python demo

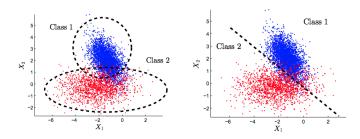
```
Single-class: https://github.com/vkanade/mlmt2017/blob/master/lecture11/Logistic%20Regression.ipynb
```

```
Multi-class: https://github.com/vkanade/mlmt2017/blob/master/lecture11/Multiclass%20Logistic%20Regression.ipynb
```

## Generative vs. Discriminative

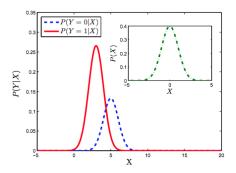
## Generative vs Discriminative Learning

- Machine learning: learn a (random) function that maps a variable X (feature) to a variable Y (class) using a (labeled) dataset  $\mathcal{D} = \{(X_1, Y_1), \dots, (X_n, Y_n)\}.$ 
  - Generative Approach: learn P(Y, X) = P(Y|X) P(X).
  - Discriminative Approach: learn P(Y|X).



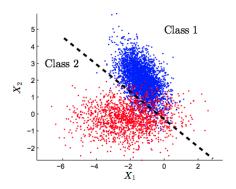
## Generative Learning

- **Generative Approach**: Finds a probabilistic model (a joint distribution P(Y,X)) that explicitly models the distribution of both the features and the corresponding labels (classes).
- Example techniques: LDA, QDA, Naive Bayes (coming soon), Hidden Markov Models, etc.



## Discriminative Learning

- **Discriminative Approach**: Finds a good fit for P(Y|X) without explicitly modeling the generative process.
- Example techniques: linear regression, logistic regression, K-nearest neighbors (coming soon), SVMs, perceptrons, etc.
- Example problem: 2 classes, separate the classes.



## Generative vs Discriminative Learning

• Generative Approach: Finds parameters that explain all data.

$$\widehat{\theta} = \underset{\theta}{\operatorname{argmax}} \sum_{i=1}^{n} \log p(x_i, y_i | \theta)$$

- Makes use of all the data.
- Flexible framework, can incorporate many tasks (e.g. classification, regression, semi-supervised learning, survival analysis, generating new data samples similar to the existing dataset, etc).
- Stronger modeling assumptions, which may not be realistic (Gaussianity, independence of features).
- Discriminative Approach: Finds parameters that help to predict only relevant data.

$$\widehat{\theta} = \operatorname*{argmin}_{\theta} \frac{1}{n} \sum_{i=1}^{n} L(y_i, f_{\theta}(x_i)) \quad \text{or} \quad \widehat{\theta} = \operatorname*{argmax}_{\theta} \sum_{i=1}^{n} \log p(y_i | x_i, \theta)$$

- Weaker modeling assumptions (thus often fewer violated assumptions and better calibration of probabilities).
- Learns to perform better on the given tasks.
- Less immune to overfitting.
- Easier to work with preprocessed data  $\phi(x)$ .

## Naïve Bayes

## Naïve Bayes

- Naïve Bayes: another plug-in classifier with a simple generative model it assumes all measured variables/features are independent given the label.
- Often used with categorical data, e.g. text document classification.
- A basic standard model for text classification consists of considering a pre-specified dictionary of p words and summarizing each document i by a binary vector  $x_i$  ("bag-of-words") where

$$x_i^{(j)} = \left\{ \begin{array}{ll} \mathbf{1} & \text{if word } j \text{ is present in document} \\ \mathbf{0} & \text{otherwise.} \end{array} \right.$$

- Presence of the word j is the j-th feature/dimension.
- To implement a plug-in classifier, we need a model for the conditional probability mass function  $g_k(x) = \mathbb{P}(X = x | Y = k)$  for each class k = 1, ..., K.

## Toy Example

#### Predict voter preference in US elections

Voted in	Annual	State	Candidate
2012?	Income		Choice
Y	50K	OK	Clinton
N	173K	CA	Clinton
Υ	80K	NJ	Trump
Υ	150K	WA	Clinton
Ν	25K	WV	Johnson
Υ	85K	IL	Clinton
:	:	:	:
Υ	1050K	NY	Trump
Ν	35K	CA	Trump
N	100K	NY	?