Absent Data in RSiena		
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Tom A.B. Snijders		
University of Oxford University of Groningen March 2023		
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2. Composition change

The case

 \Rightarrow 'Network delineation is such that, at time t_m , actor *i* or *j* is not part of the network.'

Note that network delineation is basic in network analysis, but also rather artificial / hypothetical:

it is assumed (almost) that actors outside the network do not exist.

Often, network delineation is very practical: students in a classroom, employees in a company department, firms in an industrial sector in a geographical region.

When memberships change, this can be accommodated in RSiena by using the function *sienaCompositionChange*.

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4. Structural Values

The case

⇒ 'Actors *i* and *j* are indeed part of the network at time t_m , but the tie *i* → *j* at time t_m is impossible.'

This information can be given to RSiena by specifying the tie value as a **structural zero**,

which is represented (arbitrarily) by the value $x_{ij}(t_m) = 10$.

This will specify that the simulated $X_{ij}(t) = 0$ for $t_m \le t < t_{m+1}$, and omit the values for $x_{ij}(t_m)$ and $x_{ij}(t_{m+1})$ from the calculation of estimation statistics for the MoM.

The same technique can be used to represent that actor i is absent from the network from wave m until just before wave m + 1.

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Multiple imputation: principle A good statistical method for treating missing data is multiple stochastic imputation, developed by Don Rubin. For a given incomplete data set, the missing data is imputed independently D times by drawing from the conditional distribution of the missing data given the observed data. This leads to D complete data sets. that differ only with respect to the imputed values. For each complete data set the desired analysis is executed; standard errors of parameters are a combination of the within-data set standard errors. and the variability of estimates between the data sets. Absent Data in RSiena March 2023 12/27

the larger will be the variability between imputed data sets.

Multiple Imputation: principle

How to combine the multiple imputations

The parameter of interest is denoted θ .

Suppose that the d'th randomly imputed data set leads to estimates $\hat{\theta}_d$ and estimated variances W_d ('Within').

$$W_d = \operatorname{var}\{\hat{ heta}_d \mid \operatorname{data} \operatorname{set} d\}$$
 .

Note that W_d underestimates true uncertainty. because it treats imputed data as real data.

The combined estimate is the average

$$ar{ heta}_D = rac{1}{D}\sum_{d=1}^D \hat{ heta}_d$$
 .

Multiple Imputation: principle

Combine multiple imputations....

Compute the average within-imputation variance

$$\overline{W}_D = rac{1}{D}\sum_{d=1}^D W_d$$
 ,

and the between-imputation variance

$$B_D = \frac{1}{D-1} \sum_{d=1}^{D} \left(\hat{\theta}_d - \bar{\theta}_D \right)^2.$$

Estimated total variability for $\bar{\theta}_D$ is

Multiple Imputation: principle

$$T_D = \widehat{\operatorname{var}}\Big(\bar{ heta}_D\Big) = \overline{W}_D + rac{D+1}{D}B_D$$
, s.e. $\Big(\bar{ heta}_D\Big) = \sqrt{T_D}$.

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The ratio of standard errors within the completed data sets to final standard errors can be used to define 'missing fraction' m.f.:

$$\frac{\text{diag}(W_D)}{\text{diag}(T_D)} = 1 - \text{m.f.} \; .$$

This will differ across the parameters.





6. Multiple Imputation for RSiena

Here we describe Multiple Imputation for RSiena as proposed in Krause, Huisman and Snijders, 'Multiple imputation for longitudinal network data', Italian Journal of Applied Statistics (2018).

Here the first wave is treated differently from the later waves, because for the first wave there is no previous wave.

For the later waves the ML option in RSiena will give a model-based simulation of the missings in this wave, conditional on the data of the preceding wave.

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Now back to using ML simulations for missing data imputation in RSiena.

ML simulations are used for getting model-based longitudinal imputations in the later waves, according to the steps on the next page.

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This is treated in R. Krause, M. Huisman, & T. Snijders (2018), 'Multiple imputation for longitudinal network data', *Italian Journal of Applied Statistics*:

impute first wave (for which there is no help from earlier observations!) by Bayesian ERGM or stationary SAOM, and further waves by likelihood-simulation of SAOM.

This assumes 'missingness at random': i.e., observed data are sufficient for randomly generating missing data.

However, parameters have to be estimated provisionally, and this may need to depend on the completed data sets.

The main remaining disadvantage is that the future values are not used for the imputations.

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Multiple Imputation for RSiena Example		
Example		
Waves 2-3-4 of the van de Bunt students data.		
Wave 0 is complete, so no ERGM imputation is nee	eded!	
Number of missing actors in waves 0–4 are 0; 2; 3; 5; 6, out of 32.		
Impute wave 1 – then 2 – then 3 – then 4.		

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Multiple Imputation for RSiena Example					
	default		multiple in	multiple imputation	
Effect	par.	(s.e.)	par.	(s.e.)	m.f.
Rate 1	4.207	(0.640)			
Rate 2	5.063	(0.668)			
outdegree	-1.728***	(0.317)	-1.804***	(0.343)	.16
reciprocity	2.024***	(0.233)	2.100***	(0.260)	.18
trans. trip.	0.324***	(0.048)	0.329***	(0.049)	.12
indeg pop.	0.002	(0.038)	0.024	(0.039)	.16
outdeg pop.	-0.132***	(0.027)	-0.155***	(0.031)	.11
outdeg act.	0.014	(0.014)	0.013	(0.014)	.09
sex alter	0.409*	(0.200)	0.323	(0.204)	.08
sex ego	-0.386†	(0.208)	-0.282	(0.218)	.13
same sex	0.379*	(0.189)	0.362*	(0.193)	.07
program sim.	0.604**	(0.205)	0.687**	(0.213)	.09

par. = estimate; s.e. = standard error; m.f. = missing fraction;

[†] p < 0.1; * p < 0.05; ** p < 0.01; *** p < 0.001;

convergence t ratios all < 0.06; overall maximum convergence ratio 0.08.

Note:

in waves 3 and 4 the proportion of missing actors is 0.15; proportion missing information is of about this size.

Standard errors of the two approaches are similar; estimates sometimes (3 cases) differ by about half s.e., in other cases differ hardly.

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