Introduction	Model	Example	Estimation	Dynamics of networks and behavior

# An Introduction to Stochastic Actor Oriented Models

#### Tom A.B. Snijders and Johan H. Koskinen



ReMiSS, University of Oxford Nuffield College, Oxford



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# What type of data do we want to explain Example: Studies Gerhard van de Bunt

Longitudinal study: panel design.

Study of 32 freshman university students,
7 waves in 1 year.
See van de Bunt, van Duijn, & Snijders,
*Computational & Mathematical Organization Theory*,
5 (1999), 167 – 192.

This data set can be pictured by the following graphs (arrow stands for 'best friends').



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	• •	•	• •	
	•	•		
	•	• •		
	•	•	•	
				Palek

Friendship network time 1.

Average degree 0.0; missing fraction 0.0.



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				æ
				Palek

Friendship network time 2.

Average degree 0.7; missing fraction 0.06.



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	_			Pajek

Friendship network time 3.

Average degree 1.7; missing fraction 0.09.

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				Pajek
		Friendship ı	network time 4.	

Average degree 2.1; missing fraction 0.16.

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	Á.			
				Pajek
		Friendship r	network time 5.	
				ALC: N

Average degree 2.5; missing fraction 0.19.

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	F	riendship net	work time 6.	Pajek	
				2	A

Average degree 2.9; missing fraction 0.04.

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				Pajek
		Friendship ı	network time 7	

Average degree 2.3; missing fraction 0.22.

Data represented as adjacency matrices where elements change



Data represented as adjacency matrices where elements change

$$x(t_1) = \begin{pmatrix} \cdot & \mathbf{1} & 0 & 0 & \mathbf{1} \\ 1 & \cdot & 0 & 0 & 0 \\ 1 & \mathbf{0} & \cdot & 0 & 0 \\ 0 & 0 & 0 & \cdot & 0 \\ \mathbf{1} & 0 & \mathbf{1} & \mathbf{1} & \cdot \end{pmatrix}$$



Data represented as adjacency matrices where elements change

$$x(t_2) = \begin{pmatrix} \cdot & 1 & 0 & 1 & 1 \\ 1 & \cdot & 0 & 0 & 1 \\ 1 & 1 & \cdot & 0 & 0 \\ 0 & 0 & 0 & \cdot & 0 \\ 1 & 0 & 0 & 1 & \cdot \end{pmatrix}$$



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If an element  $x_{ij}$  has changed from

$$x_{ij}(t_0)=0$$

to

$$x_{ij}(t_1)=1$$

#### something has changed inbetween $t_0$ and $t_1$















t and j SAOM for network dynamics



As evolution is observed only at a few moments we use a continuous-time model to



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 represent feedback of the process, where (unobserved) changes lead to new changes



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- o Holding times.



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#### Nodes in 2-cube



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Nodes in 2-cube



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#### Nodes in 2-cube



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#### Nodes in 2-cube



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Nodes in 2-cube



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Nodes in 2-cube

Ties between neighbouring nodes correspond to difference



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Nodes in 2-cube

Ties between neighbouring nodes correspond to difference


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Walk on 3-	-cube			



#### Graphs on 3 vertices

Corresponding 3-cube

Note one-edge difference correspond to coordinate



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### Walk on 3-cube



### Graphs on 3 vertices Corresponding 3-cube Note one-edge difference correspond to coordinate



The time between changes mostly a nuisance. The central part of SAOM is modelling the *Ministeps*. In SAOM the change of one tie-variable is seen as the outcome of a decision of one actor to make a change to one of her out-going ties .



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# Opportunity for change







Introduction	Model	Example	Estimation	Dynamics of networks and behavior

# Opportunity for change





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# Opportunity for change



Conditional on an actor having an opportunity for change the probability for each outcome



Conditional on an actor having an opportunity for change the probability for each outcome

modelled like multinomial logistic regression



Conditional on an actor having an opportunity for change the probability for each outcome

- modelled like multinomial logistic regression
- reflects the 'attractiveness' of the outcome to actor who makes change



Conditional on an actor having an opportunity for change the probability for each outcome

- modelled like multinomial logistic regression
- reflects the 'attractiveness' of the outcome to actor who makes change
- may be regarded as result of myopic optimization.



# Purpose of statistical inference:

investigate network evolution (dependent var.) as function of

- structural effects (reciprocity, transitivity, etc.)
- explanatory actor variables (independent vars.)
- explanatory dyadic variables (independent vars.)

simultaneously.



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By controlling adequately for structural effects, it is possible to test hypothesized effects of variables on network dynamics (without such control these tests would be incomplete).

The structural effects imply that the presence of ties is highly dependent on the presence of other ties.



Principles for this approach

to analysis of network dynamics:

use simulation models as models for data



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- comprise a random influence in the simulation model to account for 'unexplained variability'



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- use simulation models as models for data
- comprise a random influence in the simulation model to account for 'unexplained variability'
- use methods of statistical inference for probability models implemented as simulation models
- for panel data: employ a continuous-time model to represent unobserved endogenous network evolution
- condition on the first observation and do not model it: no stationarity assumption.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

 Actors i = 1,..., n (individuals in the network), pattern X of *ties* between them : one binary network X; X<sub>ij</sub> = 0, or 1 if there is no tie, or a tie, from *i* to *j*. Matrix X is adjacency matrix of digraph.

 $X_{ij}$  is a *tie indicator* or *tie variable*.



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  actor-dependent covariates v, dyadic covariates w.
  These can be constant or changing over time.



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  actor-dependent covariates v, dyadic covariates w.
  These can be constant or changing over time.
- Continuous time parameter t, observation moments t<sub>1</sub>,..., t<sub>M</sub>.
- Current state of network X(t) is dynamic constraint for its own change process: Markov process.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### Actor-based model:

• The actors control their outgoing ties.



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- The ties have inertia: they are *states* rather than *events*.
  At any single moment in time, only one variable X<sub>ij</sub>(t) may change.



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#### Actor-based model:

- The actors control their outgoing ties.
- The ties have inertia: they are *states* rather than *events*.
  At any single moment in time, only one variable X<sub>ij</sub>(t) may change.
- Changes are modeled as choices by actors in their outgoing ties, with probabilities depending on 'objective function' of the network state that would obtain after this change.



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The change probabilities can (but need not) be interpreted as arising from goal-directed behavior, in the weak sense of myopic stochastic optimization.

Assessment of the situation is represented by *objective function*, interpreted as 'that which the actors seem to strive after in the short run'.

Next to actor-driven models,

also tie-driven models are possible.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

At any given moment, with a given current network structure, the actors act independently, without coordination. They also act one-at-a-time.

The subsequent changes ('mini-steps') generate an endogenous dynamic context which implies a dependence between the actors over time; e.g., through reciprocation or transitive closure one tie may lead to another one.

This implies strong dependence between what the actors do, but it is completely generated by the time order: the actors are dependent because they constitute each other's changing environment.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

 waiting times until the next opportunity for a change made by actor *i*: *rate functions*;



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- waiting times until the next opportunity for a change made by actor *i*: *rate functions*;
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The distinction between rate function and objective function separates the model for *how many* changes are made from the model for *which* changes are made.



This decomposition between the timing model and the model for change can be pictured as follows:

At randomly determined moments t,

actors *i* have opportunity to change a tie variable  $X_{ij}$ :

mini step.

(Actors are also permitted to leave things unchanged.) Frequency of mini steps is determined by *rate functions*.

When a mini step is taken,

the probability distribution of the result of this step

depends on the *objective function* :

higher probabilities of moving toward new states that have higher values of the objective function.



# Specification: rate function

'how fast is change / opportunity for change ?'

Rate of change of the network by actor *i* is denoted  $\lambda_i$ : expected frequency of changes by actor *i* between observations.

Simple specification: rate functions are constant within periods.



# Specification: rate function

'how fast is change / opportunity for change ?'

Rate of change of the network by actor *i* is denoted  $\lambda_i$ : expected frequency of changes by actor *i* between observations.

Simple specification: rate functions are constant within periods.

More generally, rate functions can depend on observation period  $(t_{m-1}, t_m)$ ,

actor covariates, and network position (degrees etc.), through an exponential link function.

Formally, for a certain short time interval  $(t, t + \epsilon)$ , the probability that this actor randomly gets an opportunity to change one of his/her outgoing ties, is given by  $\epsilon \lambda_i$ .



# Specification: objective function

'what is the direction of change?'



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The objective function  $f_i(\beta, x)$  indicates preferred 'directions' of change.

 $\beta$  is a statistical parameter, *i* is the actor (node), *x* the network.

When actor *i* gets an opportunity for change, he has the possibility to change *one* outgoing tie variable  $X_{ij}$ , or leave everything unchanged.

By  $x(i \rightsquigarrow j)$  is denoted the network obtained when  $x_{ij}$  is changed ('toggled') into  $1 - x_{ij}$ . Formally,  $x(i \rightsquigarrow i)$  is defined to be equal to x.



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### Conditional on actor *i* being allowed to make a change, the probability that $X_{ii}$ changes into $1 - X_{ii}$ is

$$p_{ij}(\beta, x) = \frac{\exp\left(f_i(\beta, x(i \rightsquigarrow j))\right)}{\sum_{h=1}^n \exp\left(f_i(\beta, x(i \rightsquigarrow h))\right)},$$

and  $p_{ii}$  is the probability of not changing anything.

Higher values of the objective function indicate the preferred direction of changes.


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One way of obtaining this model specification is to suppose						
that	that actors make changes such as to optimize					
the	the objective function $f_i(\beta, x)$					
plus	a random distu	rbance the	at has a Gumbe	el distribution,		

like in random utility models in econometrics:

*myopic stochastic optimization*, multinomial logit models.

Actor *i* chooses the "best" *j* by maximizing

$$f_i(\beta, x(i \rightsquigarrow j)) + U_i(t, x, j).$$

$$\uparrow$$
random component

(with the formal definition  $x(i \rightsquigarrow i) = x$ ).



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For a convenient distributional assumption,

(*U* has type 1 extreme value = Gumbel distribution)

given that *i* is allowed to make a change,

the probability that *i* changes the tie variable to *j*,

or leaves the tie variables unchanged (denoted by j = i), is

$$p_{ij}(\beta, x) = \frac{\exp(f(i, j))}{\sum_{h=1}^{n} \exp(f(i, h))}$$

where

$$f(i,j) = f_i(\beta, \mathbf{x}(i \rightsquigarrow j))$$

and  $p_{ii}$  is the probability of not changing anything.

This is the multinomial logit form of a random utility model.



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Objective functions will be defined as sum of:





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Objective functions will be defined as sum of:

- evaluation function expressing satisfaction with network;
- 2 endowment function

expressing aspects of satisfaction with network that are obtained 'free' but are lost at a value (to allow asymmetry between creation and deletion of ties).



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Objective functions will be defined as sum of:

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expressing aspects of satisfaction with network that are obtained 'free' but are lost at a value (to allow asymmetry between creation and deletion of ties).

Evaluation function and endowment function modeled as linear combinations of theoretically argued components of preferred directions of change. The weights in the linear combination are the statistical parameters.

The focus of modeling is first on the evaluation function; then on the rate and endowment functions.



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The objective function does not reflect the eventual 'utility' of the situation to the actor, but short-time goals following from preferences, constraints, opportunities.



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The objective function does not reflect the eventual 'utility' of the situation to the actor, but short-time goals following from preferences, constraints, opportunities.

The evaluation and endowment functions express how the dynamics of the network process depends on its current state.



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Computer simulation algorithm for arbitrary rate function  $y_{i}(\alpha, \alpha)$ 

for arbitrary rate function  $\lambda_i(\alpha, \rho, x)$ 

**()** Set t = 0 and x = X(0).



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Computer simulation algorithm

for arbitrary rate function  $\lambda_i(\alpha, \rho, \mathbf{x})$ 

**)** Set 
$$t = 0$$
 and  $x = X(0)$ .

2 Generate *S* according to the exponential distribution with mean  $1/\lambda_+(\alpha, \rho, x)$  where

$$\lambda_+(\alpha,\rho,\mathbf{x}) = \sum_i \lambda_i(\alpha,\rho,\mathbf{x}) .$$



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Computer simulation algorithm

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$$\lambda_+(\alpha,\rho,\mathbf{x}) = \sum_i \lambda_i(\alpha,\rho,\mathbf{x}) .$$

Select  $i \in \{1, ..., n\}$  using probabilities

$$\frac{\lambda_i(\alpha,\rho,\mathbf{x})}{\lambda_+(\alpha,\rho,\mathbf{x})} \ .$$

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### Select $j \in \{1, ..., n\}, j \neq i$ using probabilities $p_{ij}(\beta, x)$ .



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- Select  $j \in \{1, ..., n\}, j \neq i$  using probabilities  $p_{ij}(\beta, x)$ .
- Set t = t + S and  $x = x(i \rightsquigarrow j)$ .



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Select  $j \in \{1, ..., n\}, j \neq i$  using probabilities  $p_{ij}(\beta, x)$ .

Set 
$$t = t + S$$
 and  $x = x(i \rightsquigarrow j)$ .

Go to step 2

(unless stopping criterion is satisfied).



## Model specification :

Simple specification: only evaluation function; no endowment function, periodwise constant rate function.

Evaluation function  $f_i$  reflects network effects (endogenous) and covariate effects (exogenous).



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# Model specification :

Simple specification: only evaluation function; no endowment function, periodwise constant rate function.

Evaluation function *f<sub>i</sub>* reflects network effects (endogenous) and covariate effects (exogenous). Covariates can be actor-dependentor dyad-dependent.

Convenient definition of evaluation function is a weighted sum

$$f_i(\beta, x) = \sum_{k=1}^L \beta_k \, \boldsymbol{s}_{ik}(x) \,,$$

where the weights  $\beta_k$  are statistical parameters indicating strength of effect  $s_{ik}(x)$ .



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What goes into the evaluation function?

$$x = \begin{array}{c} -0 & 1 & 0 \\ 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 0 & 0 \end{array}$$







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What goes into the evaluation function?



Satisfaction with structure of new state

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What goes into the evaluation function?



Satisfaction with structure of new state

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Choose possible network effects for actor i, e.g.: (others to whom actor i is tied are called here i's 'friends')

• out-degree effect, controlling the density / average degree,  $s_{i1}(x) = x_{i+} = \sum_j x_{ij}$ 



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Choose possible network effects for actor i, e.g.: (others to whom actor i is tied are called here i's 'friends')

- out-degree effect, controlling the density / average degree,  $s_{i1}(x) = x_{i+} = \sum_j x_{ij}$
- *reciprocity effect*, number of reciprocated ties  $s_{i2}(x) = \sum_{j} x_{ij} x_{ji}$



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Four potential effects representing network closure:

• *transitive triplets effect*, number of transitive patterns in *i*'s ties  $(i \rightarrow j, j \rightarrow h, i \rightarrow h)$  $s_{i3}(x) = \sum_{j,h} x_{ij} x_{jh} x_{ih}$ 



transitive triplet

transitive ties effect,

number of actors *j* to whom *i* is tied indirectly (through at least one intermediary:  $x_{ih} = x_{hj} = 1$ ) and also directly  $x_{ij} = 1$ ),  $s_{i4}(x) = \#\{j \mid x_{ij} = 1, \max_h(x_{ih}, x_{hj}) > 0\}$ 



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indirect ties effect,

number of actors *j* to whom *i* is tied indirectly (through at least one intermediary:  $x_{ih} = x_{hj} = 1$ ) but not directly  $x_{ij} = 0$ ), = number of geodesic distances equal to 2,

$$s_{i5}(x) = \#\{j \mid x_{ij} = 0, \max_h(x_{ih} x_{hj}) > 0\}$$



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balance or structural equivalence, similarity between outgoing ties of *i* with outgoing ties of his friends,

Example

$$s_{i6}(x) = \sum_{j=1}^{n} x_{ij} \sum_{\substack{h=1 \ h \neq i,j}}^{g} (1 - |x_{ih} - x_{jh}|) ,$$

[note that  $(1 - |x_{ih} - x_{jh}|) = 1$  if  $x_{ih} = x_{jh}$ , and 0 if  $x_{ih} \neq x_{jh}$ , so that

$$\sum_{\substack{h=1\\h\neq i,j}}^{g} \left(1 - |x_{ih} - x_{jh}|\right)$$

measures agreement between *i* and *j*.]

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Differences between these three network closure effects:

 transitive triplets effect: *i* more attracted to *j* if there are *more* indirect ties *i* → *h* → *j*;



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Differences between these three network closure effects:

- transitive triplets effect: *i* more attracted to *j* if there are *more* indirect ties *i* → *h* → *j*;
- transitive ties effect: *i* more attracted to *j* if there is *at least one* such indirect connection ;



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Differences between these three network closure effects:

- transitive triplets effect: *i* more attracted to *j* if there are *more* indirect ties *i* → *h* → *j*;
- transitive ties effect: *i* more attracted to *j* if there is *at least one* such indirect connection ;
- balance effect:
  - *i* prefers others *j* who make same choices as *i*.

Non-formalized theories usually do not distinguish between these different closure effects.

It is possible to 'let the data speak for themselves' and see what is the best formal representation of closure effects.



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in-degree related popularity effect, sum friends' in-degrees

 $s_{i7}(x) = \sum_j x_{ij} \sqrt{x_{+j}} = \sum_j x_{ij} \sqrt{\sum_h x_{hj}}$ 

related to dispersion of in-degrees

(can also be defined without the  $\sqrt{\text{sign}}$ ;



in-degree related popularity effect, sum friends' in-degrees

 $s_{i7}(x) = \sum_{j} x_{ij} \sqrt{x_{+j}} = \sum_{j} x_{ij} \sqrt{\sum_{h} x_{hj}}$ related to dispersion of in-degrees (can also be defined without the  $\sqrt{sign}$ );

out-degree related popularity effect, sum friends' out-degrees

$$s_{i8}(x) = \sum_{j} x_{ij} \sqrt{x_{j+}} = \sum_{j} x_{ij} \sqrt{\sum_{h} x_{jh}}$$

related to association in-degrees — out-degrees;

• Outdegree-related activity effect,  $s_{i9}(x) = \sum_{j} x_{ij} \sqrt{x_{i+}} = x_{i+}^{1.5}$ related to dispersion of out-degrees;

Indegree-related activity effect,
$$s_{i10}(x) = \sum_{j} x_{ij} \sqrt{x_{+i}} = x_{i+} \sqrt{x_{+i}}$$
related to association in-degrees — out-degrees;



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1 <i>th</i> nu ( <i>i</i>	<i>ree-cycle e</i> Imber of th $\rightarrow j, j \rightarrow h$	effect, ree-cycles in $h, h \rightarrow i$ )	<i>i</i> 's ties		
<b>C</b> .	$(\mathbf{v}) = \nabla$	V. V. V.		(n)	

 $s_{i11}(x) = \sum_{i,h} x_{ij} x_{jh} x_{hi}$ 



This represents a kind of generalized reciprocity, and absence of hierarchy.

2 ... and potentially many others ...



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#### Assortativity effects:

Preferences of actors dependent on their degrees. Depending on their own out- and in-degrees, actors can have differential preferences for ties to others with also high or low out- and in-degrees.

Together this yields 4 possibilities:

- out ego out alter degrees
- out ego in alter degrees
- in ego out alter degrees
- in ego in alter degrees

All these are product interactions between the two degrees.



Here also the degrees could be replaced by their square roots.

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Four kinds of evaluation function effect associated with actor covariate  $v_i$ .

This applies also to behavior variables  $Z_h$ .

Covariate-related popularity, 'alter' sum of covariate over all of *i* 's friends  $s_{i13}(x) = \sum_j x_{ij} v_j;$ 



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Four kinds of evaluation function effect associated with actor covariate  $v_i$ .

This applies also to behavior variables  $Z_h$ .

- <sup>(3)</sup> covariate-related popularity, 'alter' sum of covariate over all of *i* 's friends  $s_{i13}(x) = \sum_j x_{ij} v_j;$
- covariate-related activity, 'ego'
   i's out-degree weighted by covariate
   s<sub>i14</sub>(x) = v<sub>i</sub> x<sub>i+</sub>;



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

**(b)** *covariate-related similarity*, sum of measure of covariate similarity between *i* and his friends,  $s_{i15}(x) = \sum_j x_{ij} \sin(v_i, v_j)$ where  $\sin(v_i, v_j)$  is the similarity between  $v_i$  and  $v_j$ ,  $sim(v_i, v_j) = 1 - \frac{|v_i - v_j|}{B_{V_i}}$ ,

 $R_V$  being the range of V;



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Solution is the similarity of the similarity of

$$\operatorname{sim}(v_i, v_j) = 1 - \frac{|v_i - v_j|}{R_V},$$

 $R_V$  being the range of V;

**(6)** covariate-related interaction, 'ego  $\times$  alter'  $s_{i16}(x) = v_i \sum_j x_{ij} v_j;$ 



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Evaluation function effect for dyadic covariate  $w_{ij}$ :

covariate-related preference,

sum of covariate over all of *i*'s friends,

i.e., values of  $w_{ij}$  summed over all others to whom *i* is tied,  $s_{i17}(x) = \sum_j x_{ij} w_{ij}$ .

If this has a positive effect, then the value of a tie  $i \rightarrow j$  becomes higher when  $w_{ij}$  becomes higher.


Introduction	Model	Example	Estimation	Dynamics of networks and behavior
Example				

Data collected by Gerhard van de Bunt: group of 32 university freshmen, 24 female and 8 male students.

Three observations used here  $(t_1, t_2, t_3)$ : at 6, 9, and 12 weeks after the start of the university year. The relation is defined as a 'friendly relation'.

Missing entries  $x_{ij}(t_m)$  set to 0 and not used in calculations of statistics.

Densities increase from 0.15 at  $t_1$  via 0.18 to 0.22 at  $t_3$ .



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### Very simple model: only out-degree and reciprocity effects

	Model 1			
Effect	par.	(s.e.)		
Rate $t_1 - t_2$	3.51	(0.54)		
Rate $t_2 - t_3$	3.09	(0.49)		
Out-degree	-1.10	(0.15)		
Reciprocity	1.79	(0.27)		

rate parameters:

per actor about 3 opportunities for change between observations;

out-degree parameter negative:

on average, cost of friendship ties higher than their benefits;

reciprocity effect strong and highly significant (t = 1.79/0.27 = 6.6).



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Evaluation function is

$$f_i(x) = \sum_j \Big( -1.10 \, x_{ij} \, + \, 1.79 \, x_{ij} \, x_{ji} \Big).$$

This expresses 'how much actor *i* likes the network'.

Adding a reciprocated tie (i.e., for which  $x_{ji} = 1$ ) gives

$$-1.10 + 1.79 = 0.69$$
.

Adding a non-reciprocated tie (i.e., for which  $x_{jj} = 0$ ) gives

-1.10,

i.e., this has negative benefits.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

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-1.10,

i.e., this has negative benefits.

Gumbel distributed disturbances are added:

these have variance  $\pi^2/6 = 1.645$  and s.d. 1.28.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Conclusion: reciprocated ties are valued positively, unreciprocated ties negatively; actors will be reluctant to form unreciprocated ties; by 'chance' (the random term), such ties will be formed nevertheless and these are the stuff on the basis of which reciprocation by others can start.

(Incoming unreciprocated ties,  $x_{ji} = 1$ ,  $x_{ij} = 0$  do not play a role because for the objective function only those parts of the network are relevant that are under control of the actor, so terms not depending on the outgoing relations of the actor are irrelevant.)



Introduction	Model	Example	Estimation	Dynamics of networks and behavior
For an	interpretati	on, consider	the simple m	odel
with or	nly the trans	sitive ties net	work closure	effect. The
estima	ites are:			

#### Structural model with one network closure effect

	Mod	lel 3
Effect	par.	(s.e.)
Rate $t_1 - t_2$	3.89	(0.60)
Rate $t_2 - t_3$	3.06	(0.47)
Out-degree	-2.14	(0.38)
Reciprocity	1.55	(0.28)
Transitive ties	1.30	(0.41)



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

### Example: Personal network of ego.



for ego:

out-degree  $x_{i+} = 4$ #{recipr. ties} = 2, #{trans. ties} = 3.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

### The evaluation function is

$$f_i(x) = \sum_j \left( -2.14 \, x_{ij} \, + \, 1.55 \, x_{ij} \, x_{ji} \, + \, 1.30 \, x_{ij} \, \max_h \left( x_{ih} \, x_{hj} \right) \right)$$

$$\left( \text{ note: } \sum_{j} x_{ij} \max_{h} (x_{ih} x_{hj}) \text{ is } \# \{ \text{trans. ties } \} \right)$$

so its current value for this actor is

$$f_i(x) = -2.14 \times 4 + 1.55 \times 2 + 1.30 \times 3 = -1.56.$$



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### Options when 'ego' has opportunity for change:

	out-degr.	recipr.	trans. ties	gain	prob.
current	4	2	3	0.00	0.061
new tie to C	5	3	5	+2.01	0.455
new tie to D	5	2	4	+0.46	0.096
new tie to G	5	2	4	+0.46	0.096
drop tie to A	3	1	0	-3.31	0.002
drop tie to B	3	2	1	-0.46	0.038
drop tie to E	3	2	2	+0.84	0.141
drop tie to F	3	1	3	+0.59	0.110

The actor adds random influences to the gain (with s.d. 1.28), and chooses the change with the highest total 'value'.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

## Model with more structural effects

	Model 3		
Effect	par.	(s.e.)	
Rate $t_1 - t_2$	4.64	(0.80)	
Rate $t_2 - t_3$	3.53	(0.57)	
Out-degree	-0.90	(0.58)	
Reciprocity	2.27	(0.41)	
Transitive triplets	0.35	(0.06)	
Transitive ties	0.75	(0.45)	
Three-cycles	-0.72	(0.21)	
In-degree popularity ( $$ )	-0.71	(0.27)	

*Conclusions:* Reciprocity, transitivity; negative 3-cycle effect; negative popularity effect.



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# Add effects of gender & program, smoking similarity

	Мос	del 4
Effect	par.	(s.e.)
Rate $t_1 - t_2$	4.71	(0.80)
Rate $t_2 - t_3$	3.54	(0.59)
Out-degree	-0.81	(0.61)
Reciprocity	2.14	(0.45)
Transitive triplets	0.33	(0.06)
Transitive ties	0.67	(0.46)
Three-cycles	-0.64	(0.22)
In-degree popularity ( $$ )	-0.72	(0.28)
Sex (M) alter	0.52	(0.27)
Sex (M) ego	-0.15	(0.27)
Sex similarity	0.21	(0.22)
Program similarity	0.65	(0.26)
Smoking similarity	0.25	(0.18)

*Conclusions:* Trans. ties now not needed any more to represent transitivity; men more popular; program similarity.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

To interpret the three effects of actor covariate *gender*, it is more instructive to consider them simultaneously. Gender was coded originally by with 1 for F and 2 for M. This dummy variable was centered (mean was subtracted) but this only adds a constant to the values presented next, and does not affect the differences between them.

Therefore we may do the calculations with F = 0, M = 1.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

The joint effect of the gender-related effects for the tie variable  $x_{ij}$  from *i* to *j* is

$$-0.15 z_i + 0.52 z_j + 0.21 I\{z_i = z_j\}.$$

$i \setminus j$	F	М
F	0.21	0.52
Μ	-0.15	0.58

Conclusion:

men seem not to like female friends ...?

# Extended model specification

### 1. Endowment effect $g_i(\gamma, x, j)$

This represents the value of a tie that is lost when the tie  $i \rightarrow j$  is dissolved, but that did not play a role when the tie was created.

This model component is used when certain effects work differently for *creation* of ties  $(0 \Rightarrow 1)$  than for *termination* of ties  $(1 \Rightarrow 0)$ .



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With this extension, the relative log-probabilities are

$$f_i(\beta, \mathbf{x}(i \rightsquigarrow j)) - \mathbf{x}_{ij} \mathbf{g}_i(\gamma, \mathbf{x}, j)$$

(Note that  $x_{ij}$  is the indicator of the current tie, before the change.)

The endowment function again can be a weighted sum

$$g_i(\gamma, x, j) = \sum_{h=1}^{H} \gamma_h r_{ijh}(x) .$$



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### Examples of components of endowment function:

 $\bigcirc \gamma_1 x_{ji}$ 

 $\gamma_1$  extra benefits of a reciprocated tie.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

### Examples of components of endowment function:

- γ<sub>1</sub> x<sub>ji</sub>
  - $\gamma_{\rm 1}$  extra benefits of a reciprocated tie.
- 2 γ<sub>2</sub> W<sub>ij</sub>

effect of dyadic covariate  $w_{ij}$ 

different for creating than for breaking a tie.

In all other effects used also in the evaluation function.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

# Add endowment effect of reciprocated tie

	Mod	del 5	
Effect	par.	(s.e.)	
Rate $t_1 - t_2$	5.45	(1.00)	
Rate $t_2 - t_3$	4.05	(0.67)	
Out-degree	-0.62	(0.59)	
Reciprocity	1.39	(0.48)	
Transitive triplets	0.38	(0.06)	Transitive
Three-cycles	-0.60	(0.26)	effect omi
In-degree popularity ( $\surd$ )	-0.70	(0.26)	
Sex (M) alter	0.63	(0.26)	
Sex (M) ego	-0.29	(0.30)	
Sex similarity	0.29	(0.24)	
Program similarity	0.78	(0.28)	
Smoking similarity	0.34	(0.17)	
Endowment reciprocated tie	2.18	(0.95)	

ties tted.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior	
Evaluation effect reciprocity: 1.39					

Endowment reciprocated tie: 2.18

The overall (combined) reciprocity effect was 2.14.

With the split between the evaluation and endowment effects,

it appears now that the value of reciprocity

for creating a tie is 1.39,

and for withdrawing a tie 1.39 + 2.18 = 3.57.

Thus, there is a very strong barrier against the dissolution of reciprocated ties.



# Extended model specification

2. Non-constant rate function  $\lambda_i(\alpha, x)$ .

This means that some actors change their ties more quickly than others,

depending on covariates or network position.

Dependence on covariates:

$$\lambda_i(\alpha, \mathbf{x}) = \rho_m \exp(\sum_h \alpha_h \mathbf{v}_{hi}).$$

 $\rho_m$  is a period-dependent base rate.

(Rate function must be positive;

 $\Rightarrow$  exponential function.)



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Dependence on network position: e.g., dependence on out-degrees:

$$\lambda_i(\alpha, \mathbf{x}) = \exp(\alpha_1 \, \mathbf{x}_{i+}) \; .$$

Also, in-degrees and  $\sharp$  reciprocated ties of actor *i* may be used.

Now the parameter is  $\theta = (\rho, \alpha, \beta, \gamma)$ .



### Continuation example

Rate function depends on out-degree: those with higher out-degrees also change their tie patterns more quickly.

endowment function depends on tie reciprocation

$$g_i(\gamma, \mathbf{x}, \mathbf{j}) = \gamma_1 \, \mathbf{x}_{\mathbf{j}\mathbf{i}}$$

Reciprocity operates differently for tie initiation than for tie withdrawal.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### Parameter estimates model with rate and endowment effects

	Moo	del 6
Effect	par.	(s.e.)
Rate (period 1)	3.99	(0.70)
Rate (period 2)	2.93	(0.48)
Out-degree effect on rate	0.041	(0.034)
Out-degree	-0.79	(0.57)
Reciprocity	1.51	(0.54)
Transitive triplets	0.35	(0.05)
Three-cycles	-0.57	(0.19)
In-degree popularity ( $$ )	-0.59	(0.27)
Gender ego	-0.33	(0.31)
Gender alter	0.57	(0.27)
Gender similarity	0.30	(0.24)
Program similarity	0.80	(0.26)
Smoking similarity	0.36	(0.19)
Endowment recipr. tie	1.82	(0.97)



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

### Conclusion:

non-significant tendency that actors with higher out-degrees change their ties more often (t = 0.041/0.034 = 1.2),

value of reciprocation is larger for termination of ties than for creation (t = 1.82/0.97 = 1.88).



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

## Non-directed networks

Working paper available from:

http://www.stats.ox.ac.uk/~snijders/PoliticalAnalysis\_NetDyn.pdf

The actor-driven modeling is less straightforward for non-directed relations,

because two actors are involved in deciding about a tie.

Various modeling options are possible:

Forcing model:

one actor takes the initiative and unilaterally imposes that a tie is created or dissolved.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

 Unilateral initiative with reciprocal confirmation: one actor takes the initiative and proposes a new tie or dissolves an existing tie; if the actor proposes a new tie, the other has to confirm, otherwise the tie is not created.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

 Unilateral initiative with reciprocal confirmation: one actor takes the initiative and proposes a new tie or dissolves an existing tie; if the actor proposes a new tie, the other has to confirm, otherwise the tie is not created.

Pairwise conjunctive model: a pair of actors is chosen and reconsider whether a tie will exist between them; a new tie is formed if both agree.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

 Unilateral initiative with reciprocal confirmation: one actor takes the initiative and proposes a new tie or dissolves an existing tie; if the actor proposes a new tie, the other has to confirm, otherwise the tie is not created.

- Pairwise conjunctive model:
   a pair of actors is chosen and reconsider whether a tie
   will exist between them; a new tie is formed if both agree.
- Pairwise disjunctive (forcing) model:
   a pair of actors is chosen and reconsider whether a tie will exist between them;

a new tie is formed if at least one wishes this.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Pairwise compensatory (additive) model:
 a pair of actors is chosen and reconsider whether a tie
 will exist between them; this is based
 on the sum of their utilities for the existence of this tie.

Option 1 is close to the actor-driven model for directed relations.

In options 3–5, the pair of actors (i, j) is chosen depending on the product of the rate functions  $\lambda_i \lambda_j$ (under the constraint that  $i \neq j$ ).

The numerical interpretation of the ratio function differs between options 1–2 compared to 3–5.

The decision about the tie is taken on the basis of the objective functions  $f_i$   $f_j$  of both actors.

Introduction	Model	Example	Estimation	Dynamics of networks and behavior
2 Ectim	ation			

2. Estimation

Suppose that at least 2 observations on X(t) are available, for observation moments  $t_1$ ,  $t_2$ .

(Extension to more than 2 observations is straightforward.)

How to estimate  $\theta$ ?

Condition on  $X(t_1)$ :

the first observation is accepted as given,

contains in itself no observation about  $\theta$ .

No assumption of a stationary network distribution.

Thus, simulations start with  $X(t_1)$ .



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

## 2A. Method of moments

Choose a suitable statistic  $Z = (Z_1, \ldots, Z_K)$ ,

i.e., *K* variables which can be calculated from the network; the statistic *Z* must be *sensitive* to the parameter  $\theta$ in the sense that higher values of  $\theta_k$ lead to higher values of the expected value  $E_{\theta}(Z_k)$ ;

determine value  $\hat{ heta}$  of heta=(
ho,eta) for which

observed and expected values of suitable Z statistic are equal:

$$E_{\hat{ heta}}\left\{Z\right\} = z$$
.

Introduction	Model	Example	Estimation	Dynamics of networks and behavior
Quest	ione:			

*รนธ*อแบทอ

- What is a suitable (K-dimensional) statistic? Corresponds to objective function.
- How to find this value of  $\theta$ ?

By stochastic approximation (Robbins-Monro process) based on repeated simulations of the dynamic process, with parameter values getting closer and closer to the moment estimates.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

### Suitable statistics for method of moments

Assume first that  $\lambda_i(x) = \rho = \theta_1$ , and 2 observation moments.

This parameter determines the expected "amount of change".

A sensitive statistic for  $\theta_1 = \rho$  is

$$\mathcal{C} = \sum_{\substack{i,j=1\i
eq j}}^g \mid X_{ij}(t_2) - X_{ij}(t_1) \mid ,$$

the "observed total amount of change".



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

For the weights  $\beta_k$  in the evaluation function

$$f_i(\beta, x) = \sum_{k=1}^L \beta_k \, s_{ik}(x) \, ,$$

a higher value of  $\beta_k$  means that all actors strive more strongly after a high value of  $s_{ik}(x)$ , so  $s_{ik}(x)$  will tend to be higher for all i, k.

This leads to the statistic

$$S_k = \sum_{i=1}^n s_{ik}(X(t_2))$$

This statistic will be sensitive to  $\beta_k$ : a high  $\beta_k$  will to lead to high values of  $S_k$ .



Introduction	Model	Example	Estimation	Dynamics of networks and behavior
Momer vector	nt estimatio of statistics	n will be bas	ed on the	
		Z = (C, S)	$S_1,, S_{K-1})$ .	

Denote by *z* the observed value for *Z*. The moment estimate  $\hat{\theta}$  is defined as the parameter value for which the expected value of the statistic is equal to the observed value:



# Robbins-Monro algorithm

The moment equation  $E_{\hat{\theta}}\{Z\} = z$  cannot be solved by analytical or the usual numerical procedures, because

 $\mathsf{E}_{\theta}\{Z\}$ 

cannot be calculated explicitly.

However, the solution can be approximated by the Robbins-Monro (1951) method for stochastic approximation.

Iteration step:

$$\hat{\theta}_{N+1} = \hat{\theta}_N - a_N D^{-1}(z_N - z) , \qquad (1)$$

where  $z_N$  is a simulation of Z with parameter  $\hat{\theta}_N$ , D is a suitable matrix, and  $a_N \rightarrow 0$ .




Covariance matrix

The method of moments yields the covariance matrix

$$\mathsf{cov}(\hat{ heta}) pprox D_{ heta}^{-1} \, \Sigma_{ heta} \, D_{ heta}^{\prime \, -1}$$

where

$$\Sigma_{\theta} = \operatorname{cov}\{Z | X(t_1) = x(t_1)\}$$
  
$$D_{\theta} = \frac{\partial}{\partial \theta} \mathsf{E}\{Z | X(t_1) = x(t_1)\}.$$

Matrices  $\Sigma_{\theta}$  and  $D_{\theta}$  can be estimated from MC simulations with fixed  $\theta$ .



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

After the presumed convergence of the algorithm for approximately solving the moment equation, extra simulations are carried out

(a) to check that indeed 
$$\mathsf{E}_{\hat{\theta}} \{ Z \} \approx z$$
,

- (b) to estimate  $\Sigma_{\theta}$ ,
- (c) and to estimate  $D_{\theta}$

using a score function algorithm

(earlier algorithm used

difference quotients and common random numbers).



#### Modified estimation method:

conditional estimation .

Condition on the observed numbers of differences between successive observations,

$$c_m = \sum_{i,j} |x_{ij}(t_{m+1}) - x_{ij}(t_m)|$$
.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

For continuing the simulations do not mind the values of the time variable *t*,

but continue between  $t_m$  and  $t_{m+1}$  until the observed number of differences

$$\sum_{i,j} \mid X_{ij}(t) - x_{ij}(t_m) \mid$$

is equal to the observed  $c_m$ .

This is defined as time moment  $t_{m+1}$ .

This procedure is a bit more stable; requires modified estimator of  $\rho_m$ .



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Computer algorithm has 3 phases:

brief phase for preliminary estimation of ∂E<sub>θ</sub> {Z}/∂θ for defining D;



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Computer algorithm has 3 phases:

- brief phase for preliminary estimation of ∂E<sub>θ</sub> {Z}/∂θ for defining D;
- estimation phase with Robbins-Monro updates,
  where *a<sub>N</sub>* remains constant in *subphases* and decreases between subphases;



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Computer algorithm has 3 phases:

- brief phase for preliminary estimation of ∂E<sub>θ</sub> {Z}/∂θ for defining D;
- estimation phase with Robbins-Monro updates,
  where *a<sub>N</sub>* remains constant in *subphases* and decreases between subphases;
- final phase where θ remains constant at estimated value; this phase is for checking that

$$\mathsf{E}_{\hat{\theta}}\left\{Z\right\} \approx z$$
,

and for estimating  $D_{\theta}$  and  $\Sigma_{\theta}$  to calculate standard errors.



#### Extension: more periods

The estimation method can be extended to more than 2 repeated observations: observations x(t) for  $t = t_1, ..., t_M$ .

Parameters remain the same in periods between observations except for the basic rate of change  $\rho$  which now is given by  $\rho_m$  for  $t_m \le t < t_{m+1}$ .

For the simulations,

the simulated network X(t) is reset to the observation  $x(t_m)$  whenever the time parameter *t* passes the observation time  $t_m$ .

The statistics for the method of moments are defined as sums of appropriate statistics calculated per period ( $t_m$ ,  $t_{m+1}$ ).



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

### 2B. ML Estimation

skipped



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

The Siena program (version 4) is available as an R package, programmed by Ruth Ripley and Krists Boitmanis.

This is the package RSiena, which now includes most of the functionality in the earlier standalone version Siena 3.



### 3. Networks as dependent and independent variables

Simultaneous endogenous dynamics of networks and behavior: e.g.,

- individual humans & friendship relations: attitudes, behavior (lifestyle, health, etc.)
- individual humans & cooperation relations: work performance
- companies / organisations & alliances, cooperation: performance, organisational success.



#### Two-way influence between networks and behavior

Relational embeddedness is important for well-being, opportunities, etc.

Actors are influenced in their behavior, attitudes, performance by other actors to whom they are tied e.g., network resources (social capital), social control.

(N. Friedkin, A Structural Theory of Social Influence, C.U.P., 1998).



Introduction	Model	Example	Estimation	Dynamics of networks and behavior
In retur (friends are influ similari (e.g., M	n, many ty ship, coope uenced po ty on relev cPherson, {	pes of tie eration, liking sitively by ant attributes Smith-Lovin, &	, etc.) :: <i>homophily</i> : Cook, <i>Ann. Re</i>	ev. <i>Soc</i> ., 2001.)
More g on the (similar	enerally, a basis of the ity, opporte	ctors choose eir behavior a unities for fut	relation partn and other chai ure rewards, e	ers racteristics etc.).

*Influence*, network & behavior effects on *behavior*, *Selection*, network & behavior effects on *relations*.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior
Terminol	οαν			

relation = network = pattern of ties in group of actors; behavior = any individual-bound changeable attribute (including attitudes, performance, etc.).

Relations and behaviors are endogenous variables that develop in a simultaneous dynamics.

Thus, there is a feedback relation in the dynamics of relational networks and actor behavior / performance: macro  $\Rightarrow$  mini  $\Rightarrow$  macro  $\cdot \cdot \cdot \cdot$ 

(although network perhaps is meso rather than macro)



Introduction Model Example Estimation Dynamics of networks and behavior	Introduction	Model	Example	Estimation	Dynamics of networks and behavior
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The investigation of such social feedback processes is difficult:

- Both the network ⇒ behavior and the behavior ⇒ network effects lead 'network autocorrelation': "friends of smokers are smokers" "high-reputation firms don't collaborate with low-reputation firms". It is hard to ascertain the strengths of the causal relations in the two directions.
- For many phenomena quasi-continuous longitudinal observation is infeasible.
   Instead, it may be possible to observe networks and behaviors at a few discrete time points.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior
Data				

- One bounded set of actors
- (e.g. school class, group of professionals, set of firms);

several discrete observation moments;

for each observation moment:

- network: who is tied to whom
- behavior of all actors

Aim: disentangle effects *networks*  $\Rightarrow$  *behavior* from effects *behavior*  $\Rightarrow$  *networks*.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior
Notation:				

Integrate the *influence* (dep. var. = behavior) and *selection* (dep. var. = network) processes.

In addition to the network *X*, associated to each actor *i* there is a vector  $Z_i(t)$  of actor characteristics indexed by h = 1, ..., H. Assumption: ordered discrete (simplest case: one dichotomous variable).



### Actor-driven models

Each actor "controls" not only his outgoing ties, collected in the row vector  $(X_{i1}(t), ..., X_{in}(t))$ , but also his behavior  $Z_i(t) = (Z_{i1}(t), ..., Z_{iH}(t))$ (*H* is the number of dependent behavior variables).

Network change process and behavior change process run simultaneously, and influence each other being each other's changing constraints.





t and j SAOM for network dynamics

Introduction	Model	Example	Estimation	Dynamics of networks and behavior
At sto	chastic time	20		

(*rate functions*  $\lambda^{\chi}$  for changes in network,

```
\lambda_h^z for changes in behavior h),
```

the actors may change a tie or a behavior.

Probabilities of change are increasing functions of *objective functions* of the new state, defined specifically for network,  $f^{x}$ , and for behavior,  $f^{z}$ .

Again, only the smallest possible steps are allowed: change one tie variable,

or move one step up or down on a behavior variable.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

For network change, change probabilities are as before.

For the behaviors, the formula of the change probabilities is

$$p_{ihv}(\beta, z) = \frac{\exp(f(i, h, v))}{\sum_{k, u} \exp(f(i, k, u))}$$

where f(i, h, v) is the objective function calculated for the potential new situation after a behavior change,

$$f(i,h,v) = f_i^z(\beta, z(i,h \rightsquigarrow v)) .$$

Again, multinomial logit form.

Again, a 'maximizing' interpretation is possible.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

mini-step for change in network:

At random moments occurring at a rate  $\lambda^{x}$ , a random actor is designated to make a change in one tie variable: the *mini-step* (on  $\Rightarrow$  off, or off  $\Rightarrow$  on.)



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

mini-step for change in network:

At random moments occurring at a rate  $\lambda^x$ , a random actor is designated to make a change in one tie variable: the *mini-step* (on  $\Rightarrow$  off, or off  $\Rightarrow$  on.)

mini-step for change in behavior:

At random moments occurring at a rate  $\lambda_h^z$ , a random actor is designated to make a change in behavior *h* (one component of  $Z_i$ , assumed to be ordinal): the *mini-step* is a change to an adjacent category.

Again, many mini-steps can accumulate to big differences.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### Optimizing interpretation:

When actor *i* 'may' change an outgoing tie variable to some other actor *j*, he/she chooses the 'best' *j* by maximizing the evaluation function  $f_i^x(\beta, X, z)$  of the situation obtained after the coming network change plus a random component representing unexplained influences;

and when this actor 'may' change behavior *h*, he/she chooses the "best" change (up, down, nothing) by maximizing the evaluation function  $f_i^Z(\beta, x, Z)$  of the situation obtained after the coming behavior change plus a random component representing unexplained influences

Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Optimal network change:

The new network is denoted by  $x(i \rightsquigarrow j)$ . The attractiveness of the new situation (evaluation function plus random term) is expressed by the formula

 $f_i^{\mathsf{X}}(\beta, \mathsf{X}(i \rightsquigarrow j), \mathsf{Z}) + U_i^{\mathsf{X}}(t, \mathsf{X}, j).$   $\Uparrow$ 

random component

(Note that the network is also permitted to stay the same.)



Dynamics of networks and behavior	Estimation	Example	Model	Introduction

Optimal behavior change:

Whenever actor *i* may make a change in variable *h* of *Z*, he changes only one behavior, say  $z_{ih}$ , to the new value *v*. The new vector is denoted by  $z(i, h \rightsquigarrow v)$ .

Actor *i* chooses the "best" h, v by maximizing the objective function of the situation obtained after the coming behavior change plus a random component:

$$f_i^{z}(\beta, x, z(i, h \rightsquigarrow v)) + U_i^{z}(t, z, h, v).$$

random component

(behavior is permitted to stay the same.)



## Specification of the behavior model

Many different reasons why networks are important for behavior:

imitation :

individuals imitate others

(basic drive; uncertainty reduction).

social capital :

individuals may use resources of others;

coordination :

individuals can achieve some goals only by concerted behavior;

In this presentation, only imitation is considered, but the other two reasons are also of eminent importance.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### Basic effects for dynamics of behavior $f_i^Z$ :

$$f_i^{z}(\beta, x, z) = \sum_{k=1}^{L} \beta_k \, \boldsymbol{s}_{ik}(x, z) \,,$$

• tendency,  
$$s_{i1}^{Z}(x,z) = z_{ih}$$

*quadratic tendency*, 'effect behavior on itself',
  $s_{i2}^{Z}(x,z) = z_{ih}^{2}$  Quadratic tendency effect important for model fit.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

For a negative quadratic tendency parameter,

the model for behavior is a unimodal preference model.



For positive quadratic tendency parameters , the behavior objective function can be bimodal ('positive feedback').



Introduction		10	÷				

Substitution behavior-related average similarity, average of behavior similarities between *i* and friends  $s_{i3}(x) = \frac{1}{x_{i+}} \sum_{j} x_{ij} \sin(z_{ih}, z_{jh})$ where  $\sin(z_{ih}, z_{jh})$  is the similarity between  $v_i$  and  $v_j$ ,  $|z_{ih} - z_{ih}|$ 

$$sim(z_{ih}, z_{jh}) = 1 - \frac{|z_{ih} - z_{jh}|}{R_{Z^h}}$$

 $R_{Z^h}$  being the range of  $Z^h$ ;



Example

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$$sim(z_{ih}, z_{jh}) = 1 - \frac{|z_{ih} - z_{jh}|}{R_{Z^h}}$$

 $R_{Z^h}$  being the range of  $Z^h$ ;

average behavior alter — an alternative to similarity:  $s_{i4}(x, z) = z_{ih} \frac{1}{x_{i+}} \sum_{j} x_{ij} z_{jh}$ 

Effects 3 and 4 are alternatives for each other: they express the same theoretical idea of influence in mathematically different ways.

The data will have to differentiate between them.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Network position can also have influence on behavior dynamics e.g. through degrees rather than through behavior of those to whom one is tied:

• popularity-related tendency, (in-degree)  $s_{i5}(x, z) = z_{ih} x_{+i}$ 



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Network position can also have influence on behavior dynamics e.g. through degrees rather than through behavior of those to whom one is tied:

- activity-related tendency, (out-degree)  $s_{i8}(x, z) = z_{ih} x_{i+}$



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

• dependence on other behaviors  $(h \neq \ell)$ ,  $s_{i7}(x, z) = z_{ih} z_{i\ell}$ 

For both the network and the behavior dynamics, extensions are possible depending on the network position.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Now focus on the *similarity effect* in evaluation function :

sum of absolute behavior differences between *i* and his friends  $s_{i2}(x, z) = \sum_j x_{ij} \sin(z_{ih}, z_{jh})$ .

This is fundamental both

to network selection based on behavior,

and to behavior change based on network position.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

# A positive coefficient for this effect means that the actors prefer friends with similar $Z_h$ values (*network autocorrelation*).


Introduction	Model	Example	Estimation	Dynamics of networks and behavior

A positive coefficient for this effect means that the actors prefer friends with similar  $Z_h$  values (*network autocorrelation*).

Actors can attempt to attain this by changing their own  $Z_h$  value to the average value of their friends (*network influence, contagion*),



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

A positive coefficient for this effect means that the actors prefer friends with similar  $Z_h$  values (*network autocorrelation*).

Actors can attempt to attain this by changing their own  $Z_h$  value to the average value of their friends (*network influence, contagion*),

or by becoming friends with those with similar  $Z_h$  values (selection on similarity).



### Statistical estimation: networks & behavior

Procedures for estimating parameters in this model are similar to estimation procedures for network-only dynamics: Methods of Moments & Stochastic Approximation, conditioning on the first observation  $X(t_1), Z(t_1)$ .

The two different effects,

networks  $\Rightarrow$  behavior and behavior  $\Rightarrow$  networks,

both lead to network autocorrelation of behavior;

but they can be (in principle)

distinguished empirically by the time order: respectively association between ties at  $t_m$  and behavior at  $t_{m+1}$ ; and association between behavior at  $t_m$  and ties at  $t_{m+1}$ .



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Statistics for use in method of moments:

for estimating parameters in network dynamics:

$$\sum_{m=1}^{M-1}\sum_{i=1}^{n}s_{ik}(X(t_{m+1}),Z(t_m)),$$

and for the behavior dynamics:

$$\sum_{m=1}^{M-1}\sum_{i=1}^{n} s_{ik}(X(t_m), Z(t_{m+1})) .$$



Intro	duction	Model	Example	Estimation	Dynamics of networks and behavior

The data requirements for these models are strong: few missing data; enough change on the behavioral variable.

Currently, work still is going on about good ways for estimating parameters in these models.

Maximum likelihood estimation procedures (currently even more time-consuming; under construction...) are preferable for small data sets.



```
Model
           Example
                                                       Dynamics of networks and behavior
```

```
Example :
```

Study of smoking initiation and friendship (following up on earlier work by P. West, M. Pearson & others). One school year group from a Scottish secondary school starting at age 12-13 years, was monitored over 3 years; total of 160 pupils, of which 129 pupils present at all 3 observations; with sociometric & behavior questionnaires at three moments, at appr. 1 year intervals.

```
Smoking: values 1-3:
```

```
drinking: values 1-5;
```

covariates:

gender, smoking of parents and siblings (binary), money available (range 0-40 pounds/week).



Introduction	Model	Example	Estimation	Dynamics of networks and behavior



Introduction	Model	Example	Estimation	Dynamics of networks and behavior



Introduction	Model	Example	Estimation	Dynamics of networks and behavior



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

FIGURE 2. - OBSERVED DISTRIBUTION OF SUBSTANCE USE IN THE THREE WAVES.





Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### Simple model: friendship dynamics

Friendship dynamics	Rate 1	14.24	(1.52)
	Rate 2	10.51	(1.04)
	Outdegree	-2.95	(0.06)
	Reciprocity	1.96	(0.10)
	Popularity	0.35	(0.07)
	Transitive triplets	0.27	(0.02)
	Sex similarity	0.97	(0.10)
	Drinking alter	0.01	(0.07)
	Drinking ego	0.01	(0.08)
	Drinking ego $ imes$ drinking alter	0.17	(0.06)
	Smoking alter	-0.04	(0.08)
	Smoking ego	-0.03	(0.08)
	Smoking ego $\times$ smoking alter	0.05	(0.09)



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### Simple model: smoking and drinking dynamics

Smoking dynamics	Rate 1	5.16	(1.88)
	Rate 2	3.59	(1.24)
	Linear tendency	-3.43	(0.48)
	Quadratic tendency	2.69	(0.40)
	Ave. alter	1.89	(0.75)

Alcohol consumption dynamics	Rate 1	1.56	(0.34)
	Rate 2	2.45	(0.44)
	Linear tendency	0.47	(0.17)
	Quadratic tendency	-0.70	(0.30)
	Ave. alter	1.59	(0.83)



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Preliminary conclusion:

Significant evidence for friendship selection based on drinking behavior, and for peer influence with respect to smoking.

Weak evidence (two-sided p < .10) for peer influence with respect to drinking.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

Preliminary conclusion:

Significant evidence for friendship selection based on drinking behavior, and for peer influence with respect to smoking.

Weak evidence (two-sided p < .10) for peer influence with respect to drinking.

However, this model controls insufficiently for other influences and for the endogenous network dynamics.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### More realistic model

Friendship dynamics	Rate 1	18.67	(2.17)
	Rate 2	12.42	(1.30)
	Outdegree	-1.57	(0.27)
	Reciprocity	2.04	(0.13)
	Transitive triplets	0.35	(0.04)
	Transitive ties	0.84	(0.09)
	Three-cycles	-0.41	(0.10)
	In-degree based popularity ( $$ )	0.05	(0.07)
	Out-degree based popularity $()$	-0.45	(0.16)
	Out-degree based activity $(\sqrt{)}$	-0.39	(0.07)
	Sex alter	-0.14	(0.08)
	Sex ego	0.08	(0.10)
	Sex similarity	0.66	(0.08)
	Romantic exp. similarity	0.10	(0.06)
	Money alter (unit: 10 pounds/w)	0.11	(0.05)
	Money ego	-0.06	(0.06)
	Money similarity	0.98	(0.27)



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### More realistic model (continued)

Drinking alter	-0.01	(0.07)
Drinking ego	0.09	(0.09)
Drinking ego $ imes$ drinking alter	0.14	(0.06)
Smoking alter	-0.08	(0.08)
Smoking ego	-0.14	(0.09)
Smoking ego $\times$ smoking alter	0.03	(0.08)
	Drinking alter Drinking ego Drinking ego × drinking alter Smoking alter Smoking ego Smoking ego × smoking alter	Drinking alter $-0.01$ Drinking ego $0.09$ Drinking ego $\times$ drinking alter $0.14$ Smoking alter $-0.08$ Smoking ego $-0.14$ Smoking ego $\times$ smoking alter $0.03$



Smoking dynamics Rate 1 4.74 (1.88)   Rate 2 3.41 (1.29)   Linear tendency -3.39 (0.45)	avior	etworks and beha	ynamics of r	C	Estimation	mple	Exa	Model	Introduction
Smoking dynamics Rate 1 4.74 (1.88)   Rate 2 3.41 (1.29)   Linear tendency -3.39 (0.45)									
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Rate 2 3.41 (1.29)   Linear tendency -3.39 (0.45)			(1.88)	4.74	1	Rate 1	g dynamics	Smoking	
Linear tendency -3.39 (0.45)			(1.29)	3.41	2	Rate 2			
			(0.45)	-3.39	r tendency	Linear			
Quadratic tendency 2.71 (0.40)			(0.40)	2.71	ratic tendency	Quadra			
Ave. alter 2.00 (0.95)			(0.95)	2.00	alter	Ave. alt			
Drinking –0.11 (0.24)			(0.24)	-0.11	ing	Drinkin			
Sex (F) –0.12 (0.35)			(0.35)	-0.12	F)	Sex (F)			
Money 0.10 (0.20)			(0.20)	0.10	У	Money			
Smoking at home –0.05 (0.29)			(0.29)	-0.05	ing at home	Smokin			
Romantic experience 0.09 (0.33)			(0.33)	0.09	antic experience	Roman			



ntroduction	Model Example		Estimation	Dynamics of networks and behavio		
	Alcohol consumption dy	namics	Rate 1	1.60	(0.32)	
			Rate 2	2.50	(0.42)	
			Linear tendency	0.44	(0.17)	
			Quadratic tendency	-0.64	(0.22)	
			Ave. alter	1.34	(0.61)	
			Smoking	0.01	(0.21)	
			Sex (F)	0.04	(0.22)	
			Money	0.17	(0.16)	
			Romantic experience	-0.19	(0.27)	



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### Conclusion:

In this case, the conclusions from a more elaborate model - i.e., with better control for alternative explanations - are similar to the conclusions from the simple model.

There is evidence for friendship selection based on drinking, and for social influence with respect to smoking and drinking.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

### Parameter interpretation for behavior change

Omitting the non-significant parameters yields the following objective functions. For smoking

 $f_i^{z_1}(\hat{\beta}, x, z) =$ 

$$-3.39(z_{i1}-\bar{z}_1)+2.71(z_{i1}-\bar{z}_1)^2+2.00(z_{i1}-\bar{z}_1)(\bar{z}_{i1,fr}-\bar{z}_1),$$

where  $z_{i1}$  is smoking of actor *i*: values 1–3, mean 1.4.  $\bar{z}_{i1,fr}$  is the average smoking behavior of *i*'s friends.

Convex function - consonant with addictive behavior.









Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### For drinking the objective function (significant terms only) is

$$f_i^{z_2}(\hat{\beta}, x, z) = 0.44 (z_{i2} - \bar{z}_2) - 0.64 (z_{i2} - \bar{z}_2)^2 + 1.34 (z_{i2} - \bar{z}_2) (\bar{z}_{i2,fr} - \bar{z}_2) ,$$
  
where  $z_{i2}$  is drinking of actor *i*: values 1–5, mean 3.0.

Unimodal function - consonant with non-addictive behavior.



Introduction	Model	Example	Estimation	Dynamics

$$0.44 \left( z_{i2} - \bar{z}_2 \right) \, - \, 0.64 \left( z_{i2} - \bar{z}_2 \right)^2 \, + \, 1.34 \left( z_{i2} - \bar{z}_2 \right) \left( \bar{z}_{i2,\mathrm{fr}} - \bar{z}_2 \right)$$





Introduction	Model	Example	Estimation	Dynamics of networks and behavior

$$0.44 (z_{i2} - \bar{z}_2) - 0.64 (z_{i2} - \bar{z}_2)^2 + 1.34 (z_{i2} - \bar{z}_2) (\bar{z}_{i2, \text{fr}} - \bar{z}_2)$$



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

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Introduction	Model	Example	Estimation	Dynamics of networks and

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behavior

Introduction	Model	Example	Estimation	Dynamics of networks and behavior
Discussi	on			

- These models represent network structure as well as attributes / behavior.
- Theoretically: they combine agency and structure.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior
Disquesi	00			

- Discussion
  - These models represent network structure as well as attributes / behavior.
  - Theoretically: they combine agency and structure.
  - Available in the open source program *SIENA*, package RSiena in the statistical system R.
  - Assessing network effects is full of confounders. Don't expect results that are easy and reliable! More research is needed for range of application, interpretation, robustness.



Introduction	Model	Example	Estimation	Dynamics of networks and behavior
Discussi	<b>o</b> p			

- Discussion
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  - More research is needed for mathematical properties such as consistency, asymptotic normality, etc.



Introduction	Model	Example	Estimation	Dynamics of networks and behavio

# Why follow a statistical modeling approach to network analysis?



Introduction	Model	Example	Estimation	Dynamics of networks and behavior

# Why follow a statistical modeling approach to network analysis?

⇒ Combination of networks and attributes and: combination of structure and agency.


# Why follow a statistical modeling approach to network analysis?

- ⇒ Combination of networks and attributes and: combination of structure and agency.
- $\Rightarrow$  Distinction dependent  $\Leftrightarrow$  explanatory variables



# Why follow a statistical modeling approach to network analysis?

- ⇒ Combination of networks and attributes and: combination of structure and agency.
- $\Rightarrow$  Distinction dependent  $\Leftrightarrow$  explanatory variables
- ⇒ Hypothesis testing,
  clearer support of theory development.
- ⇒ Combination of multiple mechanisms: test theories while controlling for alternative explanations.



# Why follow a statistical modeling approach to network analysis?

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- ⇒ Hypothesis testing,
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- ⇒ Combination of multiple mechanisms: test theories while controlling for alternative explanations.
- $\Rightarrow$  Assessment of uncertainties in inference.



Goodness of fit, score tests (paper Schweinberger).



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- Bayesian estimation; Maximum Likelihood estimation (Koskinen & Snijders, J.Stat.Plann.Inf. 2007; Snijders, Koskinen & Schweinberger, Ann.Appl.Stat. 2010).



Example

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Example

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- Estimation of derivatives (Schweinberger & Snijders, Comp.Stat.Dat.An. 2006).
- Non-directed relations.



Example

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Model

**(9)** Random actor effects  $\sim$  unobserved heterogeneity.



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- Multilevel network analysis (meta analysis approach) (Snijders & Baerveldt, J.Math.Soc. 2003).



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- 8 Random effects multilevel network models.
- Valued relations; Multivariate relations.



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Introduction	Model	Example	Estimation	Dynamics of networks and behavior

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Introduction	Model	Example	Estimation	Dynamics of networks and behavior

#### A lot of material

 programs, manuals, papers, workshop announcements – can be found at the Siena website:

http://www.stats.ox.ac.uk/siena/

There is also a user's group:

http://groups.yahoo.com/groups/stocnet/

