Introduction to graph theory

Graphs

Size and order

Degree and degree distribution

Subgraphs

Paths, components

Geodesics

Some special graphs

Centrality and centralisation

Directed graphs

Dyad and triad census

Paths, semipaths, geodesics, strong and weak components

Centrality for directed graphs

Some special directed graphs

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Definition of a graph

A graph G comprises a set V of vertices and a set E of edges

Each *edge* in E is a pair (a,b) of vertices in V If (a,b) is an edge in E, we connect a and b in the *graph drawing* of G

Example:

 $V = \{1,2,3,4,5,6,7\}$ $E = \{(1,2),(1,3),(2,4).$ (4,5),(3,5),(4,5), $(5,6),(6,7)\}$

Size and order

The **size** of G is the number n of vertices in V

The *order* of G is the number L of edges in E

Minimum possible order is 0 (*empty* graph) Maximum possible order is n(n-1)/2 (*complete* graph)



Size = 7, Order = 8

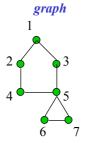
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Adjacency matrix for a graph

The adjacency matrix $\mathbf{x} = [x_{ab}]$ for G is a matrix with n rows and n colums and entries given by:

$$x_{ab} = 1$$
 if (a,b) is an edge in G
0 otherwise

Example:



adjaceny matrix 0110000

1001000 1000100 0100100

0011011 0000101 symmetric

0000101

Density

The *density* of *G* is the ratio of edges in *G* to the maximum possible number of edges

Density =
$$\frac{2L}{n(n-1)}$$



Density = $2 \times 8/(7 \times 6) = 8/21$

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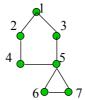
Degrees and degree sequence

The *degree* d_a of vertex a is the number of vertices to which a is linked by an edge

The minimum possible degree is 0

The maximum possible degree is *n*-1

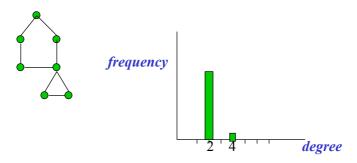
The **degree sequence** for a graph is the vector $(d_1, d_2, ..., d_n)$



Degree sequence = (2,2,2,2,4,2,2)

Degree distribution

The *degree distribution* for the graph is $(k_0, k_1, ..., k_{n-1})$, where k_i = the number of nodes with degree j

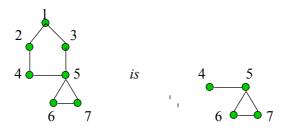


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Subgraphs

A **subgraph** of G=G(V,E) is a subset W of the vertex set V together with all of the edges that connect pairs of vertices in W

Eg if $W=\{4,5,6,7\}$, the subgraph of



Subgraph counts: the dyad census

The graph G has n(n-1)/2 subgraphs of size 2

Each subgraph of size 2 comprises a pair of vertices, and the edge between them is either present or absent:

subgraph count

•
$$D_0 = n(n-1)/2 - L$$

$$D_1 = L$$

Dyad census = (D_0, D_1) count of the no. of each type of dyad subgraph

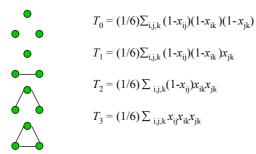
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Subgraph counts: the triad census

The graph G has n(n-1)(n-2)/6 subgraphs of size 3

Each subgraph of size 3 comprises a triple of vertices, and the possible forms are:

subgraph count



Triad census = (T_0, T_1, T_2, T_3)

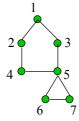
Paths

A path from vertex a to vertex b is an ordered sequence

$$a=v_0, v_1, ..., v_m=b$$

of distinct vertices in which each adjacent pair (v_{j-1}, v_j) is linked by an edge. The *length* of the path is m

There is:



a path of length 1 from 1 to 2 a path of length 2 from 1 to 4 a path of length 3 from 1 to 4 a path of length 3 from 1 to 6

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Reachability and connectedness

If there is a path from vertex a to vertex b, a is **reachable** from b

If each vertex in *G* is reachable from each other vertex, then *G* is *connected*

A *component* of *G* is a maximal connected subgraph (ie a connected subgraph with vertex set *W* for which no larger set *Z* containing *W* is connected)

A graph with 3 components



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Geodesics

A **geodesic** from a to b is a path of minimum length The **geodesic distance** d_{ab} between a and b is the length of the geodesic

If there is no path from a to b, the geodesic distance is *infinite*

For the graph

The geodesic distances are:

$$d_{AB} = 1$$
, $d_{AC} = 1$, $d_{AD} = 1$, $d_{BC} = 1$, $d_{BD} = 2$, $d_{CD} = 2$

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Cycles

A cycle is an ordered sequence

$$a=v_0, v_1, ..., v_m=a$$

of vertices in which each adjacent pair (v_{i-1}, v_i) of vertices is linked by an edge, and $v_0, v_1, ..., v_{m-1}$ are distinct. The *length* of the cycle is m

Cycles of length









Some special graphs: trivial, empty and complete graphs

The *empty* graph on 5 vertices (Z_5)



The *complete* graph on 5 vertices (K_5)



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Star and cyclic graphs

A star graph on 6 vertices

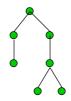


A *cyclic* graph on 5 vertices (C_5)

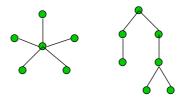


Trees and forests

A tree (a connected acyclic graph)



A *forest* (a graph with tree components)



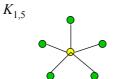
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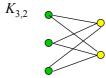
Bipartite graphs

A *bipartite* graph (vertex set can be partitioned into 2 subsets, and there are no edges linking vertices in the same set)



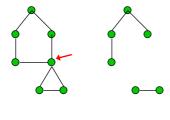
A *complete* bipartite graph (all possible edges are present)



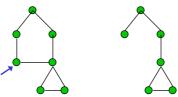


Cutpoints

A vertex is a *cutpoint* if its removal increases the number of components in the graph



the vertex marked by the red arrow is a cutpoint

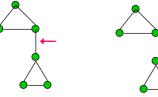


the vertex marked by the blue arrow is not

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Bridges

An edge is a *bridge* if its removal increases the number of components in the graph



the edge marked by the red arrow is a bridge

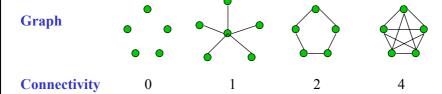
This graph has no bridges



Connectivity

The *connectivity* $\kappa(G)$ of a connected graph G is the minimum number of vertices that need to be removed to disconnect the graph (or make it empty)

A graph with more than one component has connectivity 0



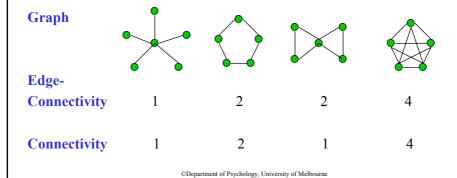
A graph with connectivity k is termed k-connected

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Edge-connectivity

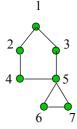
The *edge-connectivity* $\lambda(G)$ of a connected graph G is the minimum number of *edges* that need to be removed to disconnect the graph

A graph with more than one component has edge-connectivity $\boldsymbol{0}$



Independent and edge-independent paths

Two paths from a to b are *independent* if they have no nodes in common apart from a and b e.g. paths 1-2-4-5 and 1-3-5



Two paths from a to b are **edge-independent** if they have no edges in common **e.g. paths 1-2-4-5-6 and 1-3-5-7-6**

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Several theorems about connectivity

Whitney's theorem

For any graph G, $\kappa(G) \le \lambda(G) \le \delta(G)$, where $\delta(G)$ is the minimum degree of any vertex in G

Menger's theorem

A graph *G* is *k*-connected if and only if any pair of vertices in *G* are linked by at least *k* independent paths

Menger's theorem

A graph *G* is *k*-edge-connected if and only if any pair of vertices in *G* are linked by at least *k* edge-independent paths

For application, see Harary & White (2001)

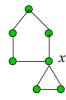
Degree Centrality

Freeman (1979) described three measures of *vertex* centrality:

Degree centrality (communication potential)

Degree centrality of node a: $C_D(a) = d_a$ degree of node a

Normalised degree centrality of node a: $d_a/(n-1)$

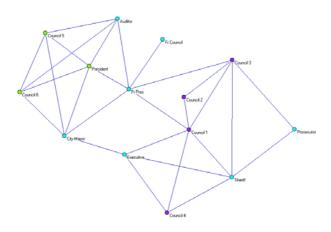


Example

Node x: degree centrality = 4 normalised degree centrality = 4/6 = 0.67

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A political network (Doreian, 1988)



Degree centrality in Doreian's (1988) political network

		Degree	NrmDegree	Share
4	Council 1	6.000	46.154	0.107
12	Fr Pres	6.000	46.154	0.107
3	Sheriff	5.000	38.462	0.089
8	President	5.000	38.462	0.089
6	Council 3	5.000	38.462	0.089
13	City Mayor	5.000	38.462	0.089
2	Auditor	4.000	30.769	0.071
1	Executive	4.000	30.769	0.071
9	Council 5	4.000	30.769	0.071
10	Council 6	4.000	30.769	0.071
7	Council 4	3.000	23.077	0.054
14	Prosecutor	2.000	15.385	0.036
5	Council 2	2.000	15.385	0.036
11	Fr Council	1.000	7.692	0.018

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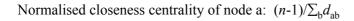
Closeness Centrality

Closeness centrality (potential for independent communication)

Closeness centrality of node a: $C_D(a) = 1/\sum_b d_{ab}$ inverse sum of

inverse sum of distances to other





Example

Node x: closeness centrality = 1/[1+1+1+1+2+2]=1/8 = 0.125normalised closeness centrality = 6/8=0.75

Closeness centrality in Doreian's political network

		Farness	nCloseness
12	Fr Pres	20.000	65.000
4	Council 1	22.000	59.091
6	Council 3	23.000	56.522
13	City Mayor	23.000	56.522
1	Executive	24.000	54.167
8	President	25.000	52.000
3	Sheriff	26.000	50.000
2	Auditor	27.000	48.148
7	Council 4	28.000	46.429
9	Council 5	31.000	41.935
10	Council 6	31.000	41.935
11	Fr Council	32.000	40.625
5	Council 2	32.000	40.625
14	Prosecutor	32.000	40.625

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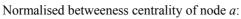
Betweeness centrality

Betweeness centrality (Potential for control of communication)

Betweenness centrality of node a: $C_D(a) = \sum_{b < c} [g_{bc(a)}/g_{bc}]$

Where g_{bc} is the number of geodesics between b and c, and $g_{bc(a)}$ is the number of geodesics between b and c that contain a

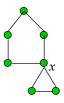
sum over all pairs (b,c) of the proportion of geodesics linking the pair that contain node a



$$2\sum_{b < c} [g_{bc(a)}/g_{bc}]/[n^2 - 3n + 2]$$

Example

Node x: betweeness centrality = 14normalised betweeness centrality = 14/[49-21+2]=7/15



Betweeness centrality in Doreian's political network

Betweenness nBetweenness

12	Fr Pres	33.198	42.561
13	City Mayor	14.490	18.578
4	Council 1	13.843	17.747
6	Council 3	13.024	16.697
1	Executive	9.452	12.118
3	Sheriff	4.500	5.769
8	President	4.021	5.156
2	Auditor	3.571	4.579
9	Council 5	0.450	0.577
10	Council 6	0.450	0.577
11	Fr Council	0.000	0.000
5	Council 2	0.000	0.000
7	Council 4	0.000	0.000
14	Prosecutor	0.000	0.000

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Maximum centrality

Centrality is at a maximum on all measures for the *central node in a star* configuration:

Normalised measures

Degree centrality: 1 Closeness centrality: 1 Betweeness centrality: 1



Centralisation

Graph-level measure of *centralisation*:

Degree to which the centrality of the most central vertex exceeds the centrality of all other vertices, compared to the maximum possible discrepancy

Index has the form:

Sum over nodes a of (max centrality in G – centrality of node a)

Max value of the sum in all graphs on the same number of vertices

Can be used with any centrality measure

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Eigenvector centrality (Bonacich, 1972)

The *eigenvector centrality* of vertex *a* is the sum of its connections to other nodes, weighted by *their* centrality

It is hence given by the solution for c_a of the equation

$$c_a = (1/\lambda) \sum_b x_{ab} c_b$$
 where λ is a constant

[Mathematical note: this is equivalent to:

$$\lambda c = xc$$

where \mathbf{x} is the adjacency matrix and \mathbf{c} is the vector of centrality measures; hence \mathbf{c} is an eigenvector of \mathbf{x} , usually taken to be the one associated with the largest eigenvalue λ]

Use with connected graphs only

Eigenvector centrality for Doreian network

Eigenvec nE	igenvec
-------------	---------

1	Executive	0.249	35.207
2	Auditor	0.287	40.585
3	Sheriff	0.257	36.368
4	Council 1	0.328	46.358
5	Council 2	0.134	18.887
6	Council 3	0.270	38.154
7	Council 4	0.186	26.357
8	President	0.350	49.435
9	Council 5	0.282	39.854
10	Council 6	0.282	39.854
11	Fr Council	0.083	11.723
12	Fr Pres	0.371	52.454
13	City Mayor	0.343	48.453
14	Prosecutor	0.118	16.655

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Directed graph

A *directed graph* G comprises a set V of vertices and a set E of *arcs*

Each **arc** in E is an **ordered pair** (a,b) of vertices in V If (a,b) is an arc in E, we draw an arc **from a to b** in the **graph drawing** of G

Example:

$$V=\{1,2,3,4\}$$
 $E=\{(1,2),(2,1),(2,4),(1,3),(4,2)\}$



Adjacency matrix for a directed graph

The adjacency matrix $\mathbf{x} = [x_{ab}]$ for G is a matrix with n rows and n colums and entries given by:

$$x_{ab}$$
 = 1 if (a,b) is an arc in G
0 otherwise

Example



adjacency matrix

 0110

 1001
 not

 0000
 necessarily

 0100
 symmetric

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Density for a directed graph

The *density* of G is the ratio of arcs in G to the maximum possible number of arcs

Density =
$$L$$

$$n(n-1)$$

Example



density = 5/12

Indegrees and outdegrees

The *indegree* i_a of vertex a is the number of vertices to which a is linked by an arc

The *outdegree* o_a of vertex a is the number of vertices linked to a by an arc

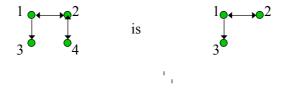
The minimum possible indegree (or outdegree) is 0The maximum possible indegree(or outdegree) is n-1

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Directed subgraphs

A *subgraph* of G=G(V,E) is a subset W of the vertex set V together with all of the arcs that connect pairs of vertices in W

Eg if $W=\{1,2,3\}$, the subgraph of



Directed subgraph counts: the dyad census

The directed graph G has n(n-1)/2 subgraphs of size 2

Each subgraph of size 2 comprises a pair of vertices, and there are either 0, 1 or 2 arcs linking them:

subgraph	count
• •	N = number of null dyads
• 	A = number of asymmetric arcs
●←→●	M = number of mutual arcs

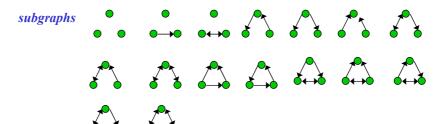
Dyad census = (M,A,N) count of the no. of each type of dyadic subgraph

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Directed subgraph counts: the triad census

The graph G has n(n-1)(n-2)/6 subgraphs of size 3

Each subgraph of size 3 comprises a triple of vertices, and there are 16 possible forms:



Triad census: counts of each of the 16 forms across all subgraphs of G

Paths and semipaths

A path from vertex a to vertex b is an ordered sequence

$$a=v_0, v_1, ..., v_m=b$$

of distinct vertices in which each adjacent pair (v_{j-1}, v_j) is linked by an *arc*. The *length* of the path is *m*

A **semipath** from vertex a to vertex b is an ordered sequence

$$a=v_0, v_1, ..., v_m=b$$

of distinct vertices in which either (v_{j-1}, v_j) and/or (v_j, v_{j-1}) is linked by an *arc*. The *length* of the semipath is m

e.g.



there is a path from 2 to 3 of length 2 there is no path from 3 to 4 there s a semipath from 3 to 4 of length 3

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Strong and weak connectedness; strong and weak components

If there is a path from vertex a to vertex b, b is **reachable** from a

If each vertex in G is reachable from each other vertex, then G is **strongly connected**

If there is a semipath from each vertex in G to each other vertex, then G is weakly connected

A *strong (weak) component* of *G* is a maximal strongly (weakly) connected subgraph (ie a strongly (weakly) connected subgraph with vertex set *W* for which no larger set *Z* containing *W* is strongly (weakly) connected)

Geodesics

A *geodesic* from a to b is a path of minimum length The *geodesic distance* d_{ab} between a and b is the length of the geodesic If there is no path from a to b, the geodesic distance is *infinite*

For the directed graph



The geodesic distances are:

$$d_{12} = 1, d_{13} = 1, d_{14} = 2,$$
 $d_{21} = 2, d_{23} = 2, d_{24} = 1,$ $d_{31} = \text{infinite}, d_{32} = \text{infinite}, d_{34} = \text{infinite},$ $d_{41} = 2, d_{42} = 1, d_{43} = 3$

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Centrality in directed graphs

As for graphs, but note that:

Indegree and outdegree centrality replace degree centrality

Eigenvector centrality is only computed by UCINET for graphs

Some special directed graphs

Empty and **complete** directed graphs





Cycle



Acyclic directed graph: a directed graph with no cycles



Transitive directed graph: every two path is accompanied by a direct path

