

## 1. Cholesky Decomposition.

- (a) Write a function with argument  $n$  to generate a random symmetric  $n \times n$ -positive definite matrix. To do this:
- generate an  $n \times n$  matrix  $C$  whose entries are independent normal random variables;
  - return  $CC^T$ .
- Check your matrices are positive definite using the `eigen()` function.
- (b) Implement the recursive Cholesky decomposition algorithm from the lecture.
- (c) Test it using your function for generating positive definite matrices, and by comparing the answers to `chol()`.
- (d) Create a function which takes a vector  $\mu$  and a symmetric positive definite matrix  $\Sigma$  and uses them to generate a multivariate normal vector  $N_n(\mu, \Sigma)$ . Your function should check that  $\Sigma$  is positive definite using `eigen()` and symmetric using `isSymmetric()`.

## 2. Sorting. Here is an algorithm called ‘Quicksort’ for sorting the objects in a vector.

Function: sort a vector  $x$

Input: vector  $x$  of length  $n$

Output: a vector  $Q(x)$  containing entries of  $x$  arranged in ascending order

1. if  $n \leq 1$  return  $x$ ;
2. pick an arbitrary ‘pivot’ element  $i \leq n$ ;
3. let  $z = (x_j \mid x_j < x_i)$  and  $y = (x_j \mid x_j > x_i)$ ;
4. let  $z' = Q(z)$  and  $y' = Q(y)$ ; [*i.e. call the algorithm on the smaller vectors*]
5. let  $x'$  be the entries in  $x$  not used in  $y$  or  $z$ ; [*i.e. any entries equal to  $x_i$* ]
6. return  $(z', x', y')$ .

- (a) Implement the algorithm in R, and test it on some random numbers.
- (b) What is the complexity if  $x_i$  is always the smallest element?
- (c) Show that, if the pivot  $x_i$  is the median element on each call, that the complexity is at most  $O(n \log_2(n))$ .

**3. Back Solving.** Here is a recursive algorithm to solve  $Ax = b$  where  $A$  is an upper triangular matrix, using back substitution.

Function: solve  $Ax = b$  for  $x$  by back-substitution  
Input:  $n \times n$  upper triangular matrix  $A$  and vector  $b$  of length  $n$   
Output: vector  $x$  of length  $n$  solving  $Ax = b$

1. If  $n = 1$  return  $x = b/A$ ;
2. create a vector  $x$  of length  $n$ ;
3. set  $x_n = b_n/A_{nn}$ ;
4. set  $b' = b_{1:(n-1)} - A_{[1:(n-1),n]}x_n$ ;
5. set  $A' = A_{[1:(n-1),1:(n-1)]}$ ;
6. solve  $A'x' = b'$  for  $x'$  by back-substitution ;
7. set  $x_{[1:(n-1)]} = x'$ ;
8. return  $x$ .

- (a) Implement this algorithm as a recursive function in R. Your function should take as input an upper triangular  $n \times n$  matrix  $A$  and return a solution  $x$  satisfying  $Ax = b$ .
- (b) For  $n = 10$ , create an  $n \times n$  upper triangular matrix  $A$  and a vector  $b$  of length  $n$ . Check the solution from your function against `backsolve()` and `solve()`.

**4. Longest Increasing Subsequence.\***

The object of this exercise is to write a function that, given a sequence of numbers  $\mathbf{a} = (a_1, \dots, a_k)$ , returns  $Q(\mathbf{a}) = (a_{s_1}, \dots, a_{s_L})$ , the longest subsequence of  $\mathbf{a}$  such that  $a_{s_1} < \dots < a_{s_L}$ . [Note that it is implicit in the idea of a subsequence that  $s_1 < \dots < s_k$ .]

- (a) Write a function that, for each  $i$ , recursively calculates the longest increasing subsequence of  $(a_1, \dots, a_{i-1}, a_i)$  that ends with  $a_i$ . [Hint: remove the final element of  $\mathbf{a}$  and invoke the function on this shorter vector; then add  $a_k$  to the longest subsequence whose final element is less than  $a_k$ .]
- (b) Use this to return a function that solves the problem of finding  $Q(\mathbf{a})$ .
- (c) Calculate the computational complexity of this method.