#### Graphs for margins of Bayesian networks.

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## Correlation does not imply causation



598 shares

They were much favoured by Margaret Thatcher, Alber

But while afternoon naps may revitalise tired brains, the according to new research.

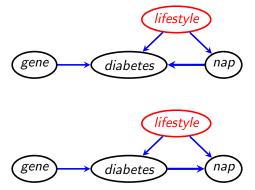
#### Abstract

#### Objectives

Atternoon napping is a common habit in China. We used data obtained from the Dongleng-Tongji cohort to examine if duration of habitual atternoon napping was associated with risks for impaired fasting plasma glucose (IFG) and diabetes mellitus (DM) in a Chinese iderky population.

Methods

## **Distinguishing Between Causal Models**



In order to compare the models, we need to understand in what ways causal models will differ, both:

- observationally;
- under interventions.

## Outline



#### Introduction





Margins of DAG Models

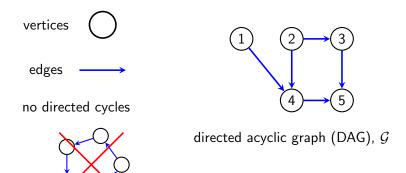






6 Summary

#### **Directed Acyclic Graphs**



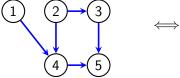
If  $w \to v$  then w is a **parent** of v:  $pa_{\mathcal{G}}(4) = \{1, 2\}$ . If  $w \to \cdots \to v$  then w is a **ancestor** of v

#### **DAG Models**



graph  $\mathcal{G}$ 

model  $\mathcal{M}(\mathcal{G})$ 



 $P: X_i \perp X_{pre(i)} \mid X_{pa(i)}[P]$ ordered local Markov property

So in example above:

$$\begin{array}{c} X_2 \perp X_1 \\ X_4 \perp X_3 \,|\, X_1, X_2 \end{array}$$

 $X_3 \perp X_1 \mid X_2$  $X_5 \perp X_1, X_2 \mid X_3, X_4$ 

#### **Global Markov Property**

P satisfies the global Markov property if for all sets A, B, C,

A d-separated from B by  $C \implies X_A \perp \!\!\!\perp X_B \,|\, X_C \,[P]$ .

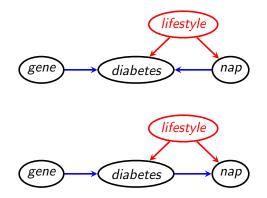
Theorem (Lauritzen et al, 1990)

 ${\it P}$  satisfies the global Markov property if and only if it satisfies the ordered local Markov property.

Point: the model can be defined in terms of 'paths of information'.

#### **Causal Interventions**

If we interpret the DAG as representing structural assumptions, then if we intervene on a node, the graph of the resulting model is just locally altered:

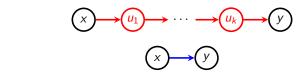


so if we force people to stop napping...

#### **Latent Projection**

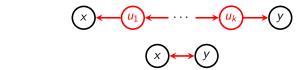
Can preserve conditional independences and causal coherence with latents using paths. DAG  $\mathcal{G}$  on vertices  $V = O \dot{\cup} U$ , define **latent projection**  $\mathcal{G}(O)$  as follows: (Verma and Pearl, 1992)

Whenever there is a path of the form



add

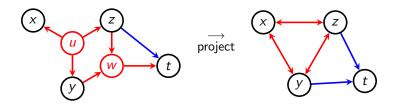
Whenever there is a path of the form



add

Then remove the latent variables U from the graph.

# ADMGs



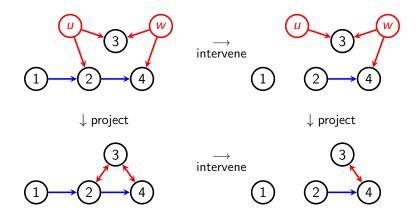
Latent projection leads to an **acyclic directed mixed graph** (ADMG) (equivalent to summary graph without undirected edges).

Can read off independences with d/m-separation. Like an ancestral graph, these are precisely observable independences from the original DAG. See Richardson (2003) for more details.

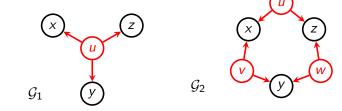
In addition, can see that projection preserves the causal structure; Verma and Pearl (1992).

#### **Causal Coherence**

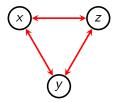
If we intervene on some observed variables, this 'breaks' their dependence upon their parents.



#### ADMGs are not sufficient



These have the same latent projection:



But the model over (x, y, z) in  $\mathcal{G}_2$  is not saturated. Still true if we dichotomize.

#### The Problem

- Verma and Pearl's latent projection only uses paths, which are inherently 'pairwise';
- the paths are objects suited to conditional independence, but not all constraints on margins are conditional independences;
- ADMGs are not a sufficiently rich class of graphs to capture the different models one can obtain.

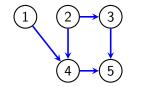
#### **Structural Equation Model View**

There is another way to think about DAG models (e.g. Lauritzen et al, 1990).

 $P \in \mathcal{M}(\mathcal{G})$  iff there exist functions  $f_i$  and independent variables  $E_i$  such that recursively setting

$$X_i = f_i(X_{\mathsf{pa}(i)}, E_i)$$

gives  $X_V$  the distribution P.

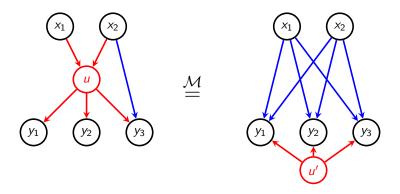


$$X_1 = f_1(E_1) 
X_2 = f_2(E_2) 
X_3 = f_3(X_2, E_3) 
X_4 = f_4(X_1, X_2, E_4) 
X_5 = f_5(X_3, X_4, E_5)$$

.

#### Simplifications

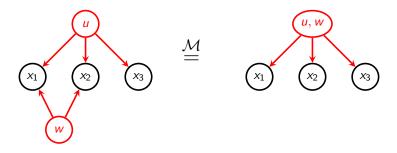
Simplification 1. WLOG latent vertices have no parents.



(Of course, this is not true if we assume a specific state-space: e.g. phylogenetic model)

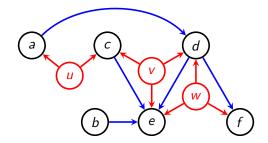
#### Simplifications

**Simplification 2.** If u, w are latent with  $ch_{\mathcal{G}}(w) \subseteq ch_{\mathcal{G}}(u)$ , then we don't need w.



## mDAGs

So we only need to consider models like this:



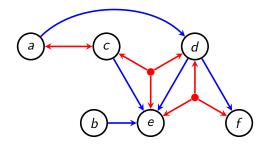
...which we represent with a hyper-graph called an mDAG.

Formally, an mDAG on V is a DAG (in blue), together with some inclusion maximal collection subsets of size at least 2 (red).

Going backwards and replacing bidirected edges with latents gives us the canonical DAG  $\bar{\mathcal{G}}.$ 

## mDAGs

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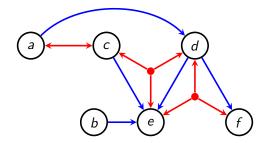


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Going backwards and replacing bidirected edges with latents gives us the **canonical DAG**  $\bar{\mathcal{G}}$ .

#### **Markov Properties**



Given an mDAG  $\mathcal{G}$  and distribution P, say P is in the **complete model** for  $\mathcal{G}$ , or  $P \in \mathcal{M}(\mathcal{G})$  if it is the margin of some distribution in the model for the canonical DAG  $\mathcal{M}(\overline{\mathcal{G}})$ .

There are other (weaker) properties Shpitser et al. (2014).

#### Latent Projection for mDAGs

For mDAG  ${\mathcal G}$  and subset of vertices O, form latent projection  $\mathfrak{p}({\mathcal G},O)$  by:

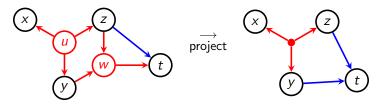
Whenever there is a path of the form

$$\begin{array}{c} (x) \longrightarrow (u_1) \longrightarrow \cdots \longrightarrow (u_k) \longrightarrow (y) \\ (x) \longrightarrow (y) \end{array}$$

add

Whenever there is a maximal set  $B = \{x_1, x_2, ..., x_k\}$  such that these variables share a hidden common cause, add hyper-edge B.

Then remove the latent variables U from the graph.



#### Results

The mDAG latent projection preserves the distinction between models.

Theorem (Evans, 2014)

If  $\mathfrak{p}(\mathcal{G}, O) = \mathfrak{p}(\mathcal{G}', O)$  then the models induced by  $\mathcal{M}(\mathcal{G})$  and  $\mathcal{M}(\mathcal{G}')$  on the margin O are the same.

So the problem which arises with ADMGs never occurs for mDAGs.

Theorem (Evans, 2014) If  $C \subseteq O$  then  $\mathfrak{p}(\mathcal{G}_{\overline{C}}, O) = \mathfrak{p}(\mathcal{G}, O)_{\overline{C}}$ ; i.e. the projection respects causal interventions.

#### **Instrumental Variables**

The Instrumental Variables model assumes causally exogenous variable z affects the treatment x.

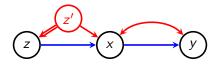
$$z \rightarrow x \rightarrow y$$

But it's well known that this is observationally indistinguishable from a hidden common cause for x and z (e.g. Didelez and Sheehan, 2007).



#### **Instrumental Variables**

To see this, imagine z is an exact copy of z'.



Doesn't really matter whether x gets information from z or z'. Very hard to see this equivalence with conditional independence

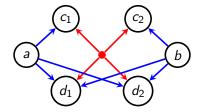
Very hard to see this equivalence with conditional independence.

#### **Instrument Generalisation**

Let  $\mathcal{G}$  have bidirected edge  $B = C \dot{\cup} D$  with:

**(**) every  $c \in C$  contained in no other bidirected edge;

Can 'split' B into C and D and add edges  $c \rightarrow d$  where necessary.

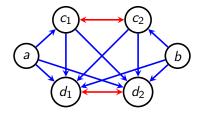


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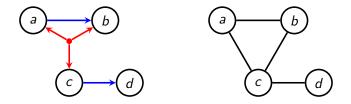
**(**) every  $c \in C$  contained in no other bidirected edge;

Can 'split' B into C and D and add edges  $c \rightarrow d$  where necessary.



#### Skeletons

Define the **skeleton** of two mDAGs as the undirected graph with v - w whenever v and w are contained in some edge together.



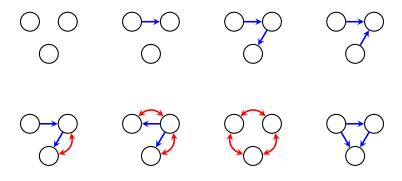
Theorem

mDAGs with different skeletons induce different models in general.

(Consequence of Theorem 4.2 of Evans, 2012)

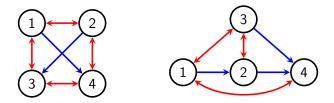
#### **Equivalence on Three Variables**

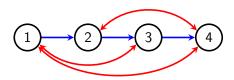
Combining the previous results, there are 8 Markov equivalence classes on three variables.



#### But Not on Four!

On four variables, it's still not clear whether or not the following models are saturated: (they are of full dimension in the discrete case)





#### Summary

We have seen that:

- graphs with 'ordinary' edges can give a causally coherent representation of marginal models;
- **but**: ordinary mixed graphs are not rich enough to represent all models;
- mDAGs provide the most general necessary framework for representing causal DAGs under marginalization;
- general Markov equivalence in this class is hard, but we're getting there!

# Thank you!

## **Main References**

Didelez and Sheehan. Mendelian Randomisation: Why Epidemiology needs a Formal Language for Causality, *SMMR*, 2007.

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Shpitser et al. Introduction to nested Markov models. *Behaviormetrika*, 2014.

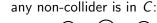
Verma. Invariant properties of causal models, *Tech Report R-134*, UCLA Cognitive Systems Laboratory, 1991.

#### d-Separation

0

A **path** is a sequence of edges in the graph; vertices may not be repeated.

A path from *a* to *b* is **blocked** by  $C \subseteq V \setminus \{a, b\}$  if either







or any collider is not in C, nor has descendants in C:



Two vertices *a* and *b* are **d-separated** given  $C \subseteq V \setminus \{a, b\}$  if **all** paths are blocked.

#### **Inequality Results**

**Can't observe**  $p^*$  **but**:

- Compatibility:  $p(0, y | z) = p^*(0, y | z)$  for each z, y; and
- Independence:  $Y \perp Z$  under  $p^*$ .

This 'compatibility' requirement turns out to place an inequality restriction on p:  $\max_{x} \sum_{z} \max_{z} p(x, y \mid z) \le 1.$ 

#### **Inequality Results**

Generalizing this argument, we find a rich theory of results on inequalities (Evans, 2012).

However these results are **not exhaustive**!

Finding **all** inequality constraints in marginal models is probably an NP hard problem.

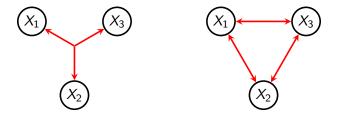
Additionally:

- fitting models with inequality constraints is not trivial;
- the usual asymptotic results do not necessarily apply.

Maybe the nested model is a good compromise!

#### ADMGs are not sufficient

In general we need to distinguish between  $\{1,2,3\}$  and  $\{1,2\},$   $\{1,3\},$   $\{2,3\}.$ 



The model on the right is not saturated. Still true if we dichotomize.

## ADMGs are not sufficient

#### Lemma

Let  $\mathcal{F}$ ,  $\mathcal{G}$ ,  $\mathcal{H}$  be mutually independent  $\sigma$ -algebrae (so that  $\mathcal{F} \perp \mathcal{G} \lor \mathcal{H}$  and so on), and let X, Y and Z be random variables such that

**(**) *X* is 
$$\mathcal{F} \lor \mathcal{G}$$
-measureable;

**(D)** Y is  $\mathcal{G} \vee \mathcal{H}$ -measureable;

$$D Z is \mathcal{F} \vee \mathcal{H} - measureable.$$

Then  $P(X = Y = Z) > 1 - \epsilon$  implies

Var  $X < 3\epsilon$ .

#### **Causal Equivalence**

The two mDAGs below are Markov equivalent, and lead to the same graph under any ordinary causal intervention.

