Advanced Simulation - Lecture 8

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February 7th, 2018

• Various proposal distributions for the Metropolis-Hastings.

• Some vizualizations to compare Metropolis-Hastings and Gibbs.

■ Gibbs sampling as a particular case of Metropolis-Hastings!

Metropolis-Hastings algorithm

- Target distribution on $\mathbb{X} = \mathbb{R}^d$ of density $\pi(x)$.
- Proposal: for any $x, x^* \in \mathbb{X}$ we have $q(x^*|x) \ge 0$ and $\int_{\mathbb{X}} q(x^*|x) dx^* = 1$.
- Starting with $X^{(1)}$, for t = 2, 3, ...

1 Sample
$$X^{\star} \sim q\left(\cdot | X^{(t-1)}\right)$$

2 Compute

$$\alpha\left(X^{\star}|X^{(t-1)}\right) = \min\left(1, \frac{\pi\left(X^{\star}\right)q\left(X^{(t-1)}\right|X^{\star}\right)}{\pi\left(X^{(t-1)}\right)q\left(X^{\star}|X^{(t-1)}\right)}\right)$$

3 Sample $U \sim \mathcal{U}_{[0,1]}$. If $U \leq \alpha \left(X^* | X^{(t-1)} \right)$, set $X^{(t)} = X^*$, otherwise set $X^{(t)} = X^{(t-1)}$.

Sophisticated Proposals

 \blacksquare "Langevin" proposal relies on

$$X^{\star} = X^{(t-1)} + \frac{\sigma}{2} \nabla \log \pi |_{X^{(t-1)}} + \sigma W$$

where $W \sim \mathcal{N}(0, I_d)$, so the Metropolis-Hastings acceptance ratio is

$$\frac{\pi(X^*)q(X^{(t-1)} \mid X^*)}{\pi(X^{(t-1)})q(X^* \mid X^{(t-1)})} = \frac{\pi(X^*)}{\pi(X^{(t-1)})} \frac{\mathcal{N}(X^{(t-1)}; X^* + \frac{\sigma}{2} \cdot \nabla \log \pi|_{X^*}; \sigma^2)}{\mathcal{N}(X^*; X^{(t-1)} + \frac{\sigma}{2} \cdot \nabla \log \pi|_{X^{(t-1)}}; \sigma^2)}.$$

Possibility to use higher order derivatives:

$$X^{\star} = X^{(t-1)} + \frac{\sigma}{2} \left[\nabla^2 \log \pi |_{X^{(t-1)}} \right]^{-1} \nabla \log \pi |_{X^{(t-1)}} + \sigma W.$$

\blacksquare We can use

$$q(X^{\star}|X^{(t-1)}) = g(X^{\star};\varphi(X^{(t-1)}))$$

where g is a distribution on X of parameters $\varphi(X^{(t-1)})$ and φ is a deterministic mapping

$$\frac{\pi(X^{\star})q(X^{(t-1)}|X^{\star})}{\pi(X^{(t-1)})q(X^{\star}|X^{(t-1)})} = \frac{\pi(X^{\star})g(X^{(t-1)};\varphi(X^{\star}))}{\pi(X^{(t-1)})g(X^{\star};\varphi(X^{(t-1)}))}.$$

• For instance, use heuristics borrowed from optimization techniques.

The following link shows a comparison of

- \blacksquare adaptive Metropolis-Hastings,
- Gibbs sampling,
- No U-Turn Sampler (e.g. Hamiltonian MCMC)

on a simple linear model.

twiecki.github.io/blog/2014/01/02/visualizing-mcmc/ $\,$

Sophisticated Proposals

- Assume you want to sample from a target π with $\operatorname{supp}(\pi) \subset \mathbb{R}^+$, e.g. the posterior distribution of a variance/scale parameter.
- Any proposed move, e.g. using a normal random walk, to ℝ[−] is a waste of time.
- Given $X^{(t-1)}$, propose $X^* = \exp(\log X^{(t-1)} + \varepsilon)$ with $\varepsilon \sim \mathcal{N}(0, \sigma^2)$. What is the acceptance probability then?

$$\alpha(X^* \mid X^{(t-1)}) = \min\left(1, \frac{\pi(X^*)}{\pi(X^{(t-1)})} \frac{q(X^{(t-1)} \mid X^*)}{q(X^* \mid X^{(t-1)})}\right)$$
$$= \min\left(1, \frac{\pi(X^*)}{\pi(X^{(t-1)})} \frac{X^*}{X^{(t-1)}}\right).$$

Why?

Random Proposals

• Assume you want to use $q_{\sigma^2}(X^*|X^{(t-1)}) = \mathcal{N}(X; X^{(t-1)}, \sigma^2)$ but you don't know how to pick σ^2 . You decide to pick a random $\sigma^{2,*}$ from a distribution $f(\sigma^2)$:

$$\sigma^{2,\star} \sim f(\sigma^{2,\star}), \ X^{\star} | \sigma^{2,\star} \sim q_{\sigma^{2,\star}}(\cdot | X^{(t-1)})$$

so that

$$q(X^{\star}|X^{(t-1)}) = \int q_{\sigma^{2,\star}}(X^{\star}|X^{(t-1)})f(\sigma^{2,\star})d\sigma^{2,\star}.$$

• Perhaps $q(X^*|X^{(t-1)})$ cannot be evaluated, e.g. the above integral is intractable. Hence the acceptance probability

$$\min\{1, \frac{\pi(X^{\star})q(X^{(t-1)}|X^{\star})}{\pi(X^{(t-1)})q(X^{\star}|X^{(t-1)})}\}$$

cannot be computed.

Instead you decide to accept your proposal with probability

$$\alpha_{t} = \min\left\{1, \frac{\pi\left(X^{\star}\right)q_{\sigma^{2,(t-1)}}\left(X^{(t-1)}\right|X^{\star}\right)}{\pi\left(X^{(t-1)}\right)q_{\sigma^{2,\star}}\left(X^{\star}|X^{(t-1)}\right)}\right\}$$

where $\sigma^{2,(t-1)}$ corresponds to parameter of the last accepted proposal.

- With probability α_t , set $\sigma^{2,(t)} = \sigma^{2,\star}$, $X^{(t)} = X^{\star}$, otherwise $\sigma^{2,(t)} = \sigma^{2,(t-1)}$, $X^{(t)} = X^{(t-1)}$.
- **Question**: Is it valid? If so, why?

Random Proposals

 \blacksquare Consider the extended target

$$\widetilde{\pi}(x,\sigma^2) := \pi(x) f(\sigma^2).$$

 \blacksquare Previous algorithm is a Metropolis-Hastings of target $\widetilde{\pi}(x,\sigma^2)$ and proposal

$$q(y,\tau^2|x,\sigma^2)=f(\tau^2)q_{\tau^2}(y|x)$$

■ Indeed, we have

$$\begin{split} & \frac{\widetilde{\pi}(y,\tau^2)}{\widetilde{\pi}(x,\sigma^2)} \frac{q(x,\sigma^2|y,\tau^2)}{q(y,\tau^2|x,\sigma^2)} \\ &= \frac{\pi(y)f(\tau^2)}{\pi(x)f(\sigma^2)} \frac{f(\sigma^2)q_{\sigma^2}(x|y)}{f(\tau^2)q_{\tau^2}(y|x)} = \frac{\pi(y)}{\pi(x)} \frac{q_{\sigma^2}(x|y)}{q_{\tau^2}(y|x)} \end{split}$$

Remark: we just need to be able to sample from $f(\cdot)$, not to evaluate it.

Using multiple proposals

- Consider a target of density $\pi(x)$ where $x \in \mathbb{X}$.
- To sample from π , you might want to use various proposals for Metropolis-Hastings $q_1(x'|x), q_2(x'|x), ..., q_p(x'|x)$.
- One way to achieve this is to build a proposal

$$q(x'|x) = \sum_{j=1}^{p} \beta_j q_j(x'|x), \ \beta_j > 0, \sum_{j=1}^{p} \beta_j = 1,$$

and Metropolis-Hastings requires evaluating

$$\alpha\left(X^{\star}|X^{(t-1)}\right) = \min\left(1, \frac{\pi\left(X^{\star}\right)q\left(X^{(t-1)}|X^{\star}\right)}{\pi\left(X^{(t-1)}\right)q\left(X^{\star}|X^{(t-1)}\right)}\right),$$

and thus evaluating $q_j(X^*|X^{(t-1)})$ for j = 1, ..., p.

Lecture 8

Let

$$q(x'|x) = \beta_1 \mathcal{N}(x'; x, \Sigma) + (1 - \beta_1) \mathcal{N}(x'; \mu(x), \Sigma)$$

where $\mu : \mathbb{X} \to \mathbb{X}$ is a clever but computationally expensive deterministic optimisation algorithm.

• Using $\beta_1 \approx 1$ will make most proposed points come from the cheaper proposal distribution $\mathcal{N}(x'; x, \Sigma)$...

• ... but you won't save time as $\mu(X^{(t-1)})$ needs to be evaluated at every step.

Composing kernels

- How to use different proposals to sample from π without evaluating all the densities at each step?
- What about combining different Metropolis-Hastings updates K_j using proposal q_j instead? i.e.

$$K_{j}(x, x') = \alpha_{j}(x'|x)q_{j}(x'|x) + (1 - a_{j}(x))\delta_{x}(x')$$

where

$$\alpha_j(x'|x) = \min\left(1, \frac{\pi(x')q_j(x|x')}{\pi(x)q_j(x'|x)}\right)$$
$$a_j(x) = \int \alpha_j(x'|x)q_j(x'|x)dx'.$$

Generally speaking, assume

- p possible updates characterised by kernels $K_j(\cdot, \cdot)$,
- each kernel K_j is π -invariant.

Two possibilities of combining the p MCMC updates:

- **Cycle**: perform the MCMC updates in a deterministic order.
- **Mixture**: Pick an MCMC update at random.

Cycle of MCMC updates

• Starting with $X^{(1)}$ iterate for t = 2, 3, ...

1 Set
$$Z^{(t,0)} := X^{(t-1)}$$
.
2 For $j = 1, ..., p$, sample $Z^{(t,j)} \sim K_j \left(Z^{(t,j-1)}, \cdot \right)$.
3 Set $X^{(t)} := Z^{(t,p)}$.

■ Full cycle transition kernel is

$$K\left(x^{(t-1)}, x^{(t)}\right) = \int \cdots \int K_1\left(x^{(t-1)}, z^{(t,1)}\right) K_2\left(z^{(t,1)}, z^{(t,2)}\right)$$
$$\cdots K_p\left(z^{(t,p-1)}, x^{(t)}\right) dz^{(t,1)} \cdots dz^{(t,p-1)}.$$

• K is π -invariant.

Mixture of MCMC updates

• Starting with $X^{(1)}$ iterate for t = 2, 3, ...

1 Sample
$$J$$
 from $\{1, ..., p\}$ with $\mathbb{P}(J = k) = \beta_k$.
2 Sample $X^{(t)} \sim K_J(X^{(t-1)}, \cdot)$.

• Corresponding transition kernel is

$$K\left(x^{(t-1)}, x^{(t)}\right) = \sum_{j=1}^{p} \beta_j K_j\left(x^{(t-1)}, x^{(t)}\right)$$

- K is π -invariant.
- The algorithm is *different* from using a mixture proposal

$$q(x'|x) = \sum_{j=1}^{p} \beta_j q_j(x'|x).$$

Metropolis-Hastings Design for Multivariate Targets

- If dim (X) is large, it might be very difficult to design a "good" proposal q(x'|x).
- As in Gibbs sampling, we might want to partition x into $x = (x_1, ..., x_d)$ and denote $x_{-j} := x \setminus \{x_j\}$.
- We propose "local" proposals where only x_j is updated

$$q_j(x'|x) = \underbrace{q_j(x'_j|x)}_{\delta_{x_{-j}}(x'_{-j})}$$
 $\underbrace{\delta_{x_{-j}}(x'_{-j})}_{\delta_{x_{-j}}(x'_{-j})}$

propose new component j keep other components fixed

.

Metropolis-Hastings Design for Multivariate Targets

This yields

$$\begin{aligned} \alpha_j(x,x') &= \min\left(1, \frac{\pi(x'_{-j},x'_j)q_j(x_j|x_{-j},x'_j)}{\pi(x_{-j},x_j)q_j(x'_j|x_{-j},x_j)}\underbrace{\delta_{x'_{-j}}(x_{-j})}_{=1}\right) \\ &= \min\left(1, \frac{\pi(x_{-j},x'_j)q_j(x_j|x_{-j},x_j)}{\pi(x_{-j},x_j)q_j(x'_j|x_{-j},x_j)}\right) \\ &= \min\left(1, \frac{\pi_{X_j|X_{-j}}(x'_j|x_{-j})q_j(x_j|x_{-j},x_j)}{\pi_{X_j|X_{-j}}(x_j|x_{-j})q_j(x'_j|x_{-j},x_j)}\right).\end{aligned}$$

One-at-a-time MH (cycle/systematic scan)

Starting with $X^{(1)}$ iterate for t = 2, 3, ...For j = 1, ..., d,

• Sample $X^{\star} \sim q_j(\cdot | X_1^{(t)}, \dots, X_{j-1}^{(t)}, X_j^{(t-1)}, \dots, X_d^{(t-1)}).$

Compute

$$\begin{split} \alpha_{j} &= \min\left(1, \frac{\pi_{X_{j}|X_{-j}}\left(X_{j}^{\star} \mid X_{1}^{(t)} \dots X_{j-1}^{(t)}, X_{j+1}^{(t-1)} \dots X_{d}^{(t-1)}\right)}{\pi_{X_{j}|X_{-j}}\left(X_{j}^{(t-1)} \mid X_{1}^{(t)} \dots X_{j-1}^{(t)}, X_{j+1}^{(t-1)} \dots X_{d}^{(t-1)}\right)} \right) \\ &\times \frac{q_{j}\left(X_{j}^{(t-1)} \mid X_{1}^{(t)} \dots X_{j-1}^{(t)}, X_{j}^{\star}, X_{j+1}^{(t-1)} \dots X_{d}^{(t-1)}\right)}{q_{j}\left(X_{j}^{\star} \mid X_{1}^{(t)} \dots X_{j-1}^{(t)}, X_{j}^{(t-1)}, X_{j+1}^{(t-1)} \dots X_{d}^{(t-1)}\right)}\right). \end{split}$$

• With probability
$$\alpha_j$$
, set $X^{(t)} = X^*$, otherwise set $X^{(t)} = X^{(t-1)}$.

One-at-a-time MH (mixture/random scan)

Starting with $X^{(1)}$ iterate for t = 2, 3, ...

- Sample J from $\{1, ..., d\}$ with $\mathbb{P}(J = k) = \beta_k$.
- Sample $X^{\star} \sim q_J\left(\cdot | X_1^{(t-1)}, ..., X_d^{(t-1)}\right)$.

Compute

$$\alpha_{J} = \min\left(1, \frac{\pi_{X_{J}|X_{-J}}\left(X_{J}^{\star} \mid X_{1}^{(t-1)} \dots X_{J-1}^{(t-1)}, X_{J+1}^{(t-1)} \dots\right)}{\pi_{X_{J}|X_{-J}}\left(X_{J}^{(t-1)} \mid X_{1}^{(t-1)} \dots X_{J-1}^{(t-1)}, X_{J+1}^{(t-1)} \dots\right)} \times \frac{q_{J}\left(X_{J}^{(t-1)} \mid X_{1}^{(t-1)} \dots X_{J-1}^{(t-1)}, X_{J}^{\star}, X_{J+1}^{(t-1)} \dots X_{d}^{(t-1)}\right)}{q_{J}\left(X_{J}^{\star} \mid X_{1}^{(t-1)} \dots X_{J-1}^{(t-1)}, X_{J}^{(t-1)}, X_{J+1}^{(t-1)} \dots X_{d}^{(t-1)}\right)}\right).$$

• With probability α_J set $X^{(t)} = X^*$, otherwise $X^{(t)} = X^{(t-1)}$.

Gibbs Sampler as a Metropolis-Hastings algorithm

 Proposition. The systematic Gibbs sampler is a cycle of one-at-a time MH whereas the random scan Gibbs sampler is a mixture of one-at-a time MH where

$$q_j\left(x'_j\middle|x\right) = \pi_{X_j|X_{-j}}\left(x'_j\middle|x_{-j}\right).$$

■ *Proof.* It follows from

$$\frac{\pi \left(x_{-j}, x_{j}' \right)}{\pi \left(x_{-j}, x_{j} \right)} \frac{q_{j} \left(x_{j} | x_{-j}, x_{j}' \right)}{q_{j} \left(x_{j}' | x_{-j}, x_{j} \right)}$$

$$= \frac{\pi \left(x_{-j} \right) \pi_{X_{j} | X_{-j}} \left(x_{j}' | x_{-j} \right)}{\pi \left(x_{-j} \right) \pi_{X_{j} | X_{-j}} \left(x_{j} | x_{-j} \right)} \frac{\pi_{X_{j} | X_{-j}} \left(x_{j} | x_{-j} \right)}{\pi_{X_{j} | X_{-j}} \left(x_{j} | x_{-j} \right)}$$

$$= 1.$$

This is not a Gibbs sampler

Consider a case where d = 2. From $X_1^{(t-1)}, X_2^{(t-1)}$ at time t-1:

• Sample $X_1^{\star} \sim \pi(X_1 \mid X_2^{(t-1)})$, then $X_2^{\star} \sim \pi(X_2 \mid X_1^{\star})$. The proposal is then $X^{\star} = (X_1^{\star}, X_2^{\star})$.

Compute

$$\alpha_t = \min\left(1, \frac{\pi(X_1^{\star}, X_2^{\star})}{\pi(X_1^{(t-1)}, X_2^{(t-1)})} \frac{q(X^{(t-1)} \mid X^{\star})}{q(X^{\star} \mid X^{(t-1)})}\right)$$

• Accept X^* or not based on α_t , where here

$$\alpha_t \neq 1$$

!!